Basic Forest Cover Mapping using Digitized Remote Sensor Data and Automatic Data Processing Techniques ¹

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ABSTRACT

Increasing demands on the forest resource will necessitate increasingly more intensive management in the future. In order to achieve this goal, reliable and timely information over large geographic areas will be required. Remote sensing techniques offer much potential for the procurement of such information.

This research, then, was pointed toward study of that potential. Four objectives were established as follows:

1) to determine the optimum number of the available twelve multispectral scanner (MSS) wavelength bands to use for forest cover mapping with automatic data processing (ADP) techniques; 2) to determine the current capability to map basic forest cover using MSS data and ADP techniques; 3) to determine the relative utility, to forest cover mapping,

of the four spectral regions available in the twelve-channel MSS data (i.e. visible, and near, middle and thermal infrared); and 4) to compare the accuracy of digitized color infrared photography with that of MSS data for forest cover mapping using ADP techniques.

In attaining the first objective, statistics defining the six cover type classes of interest (deciduous forest, coniferous forest, water, forage, corn, and soybeans) were calculated and used by the computer as a basis for the selection of "best" wavelength band combinations ranging in size from one through ten wavelength bands each. With the spectral information contained in each of these combinations, and with all twelve channels, the entire test area was classified into the six defined classes, using the LARSYS programs. Tests of the computer's performance indicated that the use of five wavelength bands would fulfill the dual requirements of adequate accuracy and moderate computer time.

In fulfilling the second objective, the automatically selected "best" combination of five channels (one each from the green and red visible wavelengths, and the near, middle and thermal infrared wavelengths) produced classification accuracies in excess of 90 percent for deciduous and coniferous forest. When these two classes were grouped, the accuracy for combined forest was in excess of 95 percent. The use of all twelve channels caused only a slight increase in overall accuracy.

In satisfying the third objective, the LARSYS feature selection processor was allowed to consider wavelength bands constituting only various subsets of the four spectral regions. On this basis, it selected a number of five-channel combinations. Classifications performed by these various channel combinations indicate that the visible wavelengths are sufficiently accurate for classifying combined forest, but inadequate for differentiating between deciduous and coniferous forest. The infrared channels separated the two forest classes with reasonable accuracy, but allowed confusion between forest and the agricultural classes. deletion of either the near or the middle infrared individually, did not reduce accuracies, but, when both were deleted, accuracies dropped drastically. The deletion of the thermal infrared had little effect on forest cover mapping but did allow considerable confusion among the agricultural cover types. These results indicate that the thermal infrared is desirable, but not necessary, for basic forest cover mapping, and that accurate classification of deciduous and coniferous forest cover can be achieved with the visible plus either the near or middle infrared spectral regions.

To meet the fourth objective, small-scale color infrared photography, acquired the same day over the test site, was color separated, digitized in three wavelength bands and, automatically classified. In general, the digitized photography was inadequate for automatic forest cover mapping and compared poorly to the MSS data results when similar wavelength bands were used. These results were apparently caused by the narrower dynamic range, poorer spectral resolution, and uneven illumination (due to vignetting and the anti-solar point) of the photographic data.

CHAPTER I

INTRODUCTION

Introductory Statement

Forests have long been recognized as important natural and renewable resources. Thus, when the management of our forests was first begun, it was primarily for the purpose of improving the production of wood and fiber. Later, the importance of the forest to the production of water and the protection and nurturing of wildlife resulted in a general broadening of management objectives. Today, the steady increase in size of our population and the trend toward urbanization has lead to a much greater reliance on the forest resources, as well as an additional and rapidly growing demand for wilderness oriented recreation.

However, despite the fact that the demands on the forest continue to increase, the forest resource base does not. It, in fact, decreases. Urban development and highway construction, for instance, destroy many acres of forest land each year.

The demand for forest recreation, plus an increased awareness of the natural environment, has resulted in the redistribution of some public forest lands to non-commercial management objectives. In addition, environmental organizations have successfully demanded the implementation of management and harvesting practices more compatible with the protection of the environment.

These increasing demands on the forest in general, and commercial forests in particular, are underlining the need for more efficient and intensive management. However, the attainment of this goal is complicated by several factors, the first of which is the fact that our forest lands are not under the control of one unified management agency. Though the U.S. Forest Service controls more timberland than any other single organization, there are other agencies at the federal government level, plus hundreds of state and local agencies, who are also responsible for the management of forest lands. Nor does this exhaust the list of organizations involved since the private sector, especially industry, controls large amounts of often intensively-managed timberland.

This diversity of management groups, with its accompanying multiplicity of management goals, makes a single,
closely-coordinated management scheme, difficult to achieve.

A second factor is that, although the forest is admittedly a valuable resource, the per-acre economic return

is generally quite marginal. Economics must therefore be considered as a part of any management scheme and the problem of gathering information about a geographically extensive resource (covering roughly a third of the United States) becomes one of acquiring data not only adequate for management purposes, but also at a minimum per-acre expense.

In the past, the periodic national forest surveys, (undertaken at ten-year intervals at an average cost of about six cents per acre) (Glazebrook, 1973), have served as a reasonably satisfactory resource inventory. However, as the demand for goods and services from the forest continues to increase, so does the need for more timely information over vast geographic areas.

One tool which shows promise for the solution of this problem is "remote sensing," defined by Hoffer (1971) as follows:

"Remote sensing is the discipline involved with the gathering of data about the earth's surface or near-surface environment through the use of a variety of sensor systems that are usually borne by aircraft or spacecraft, and the processing of these data into information useful for the understanding and managing of man's environment."

Remote sensing equipment, mounted in high-flying aircraft or spacecraft, offers the capability to gather large
amounts of data over extensive areas in a very short time.
The National Aeronautics and Space Administration's Earth
Resources Technology Satellite (ERTS), for instance, can obtain data for the entire surface of the earth every eighteen

days, producing computer-compatible data tapes and 1:1,000,000 scale, 9-inch x 9-inch frames of imagery, each of which covers 13,243 square miles of terrain (Hoffer, 1971). Such small-scale imagery could serve as the third stage in a multi-stage sampling scheme (Langley et al., 1969, Glazebrook, 1973).

If the past performance of ERTS and other types of remote sensor data-gathering equipment is any indication, it may be assumed that data acquisition is, and will continue to be a less difficult problem than that of reducing the huge amounts of data acquired to useful information (Hoffer, 1972, Hoffer, 1971). This study, therefore, is concerned with several questions pertaining to the extraction, from remotely-sensed data, of information applicable to forest management.

There are two basic methods of deriving such useful information from remotely-sensed imagery. Most familiar and wisely used are the techniques of photo-interpretation, in which a scientist trained in photo-interpretation manually derives information from the imagery, basing his decisions on the image elements of size, shape, tone or color, texture, pattern, association and, of course, experience in both his own particular discipline and as a photo-interpreter (Hoffer et al., 1968, American Society of Photogrammetry, 1968). The second method is based on automatic data processing (ADP) techniques. In this method, a computerized pattern

recognition algorithm is "trained" to recognize and categorize various cover types of interest based on spectral (tone) characteristics as recorded by the imaging device. It is the latter data reduction method with which this study is primarily concerned.

of the variety of sensor systems available, this study is concerned only with the two most commonly used. The oldest, and most highly developed, is the photographic system, with a variety of films and filters available. The second system of interest (primarily because of the more quantitative format and spectral range of the data acquired) is the multispectral scanner (MSS). (A brief description of the University of Michigan's twelve-channel airborne scanner, which was used to acquire the MSS data used in this study, will follow in the Review of Literature). Another type of multispectral scanner, the data from which is currently the focus of a great deal of research and analysis, is aboard the 1972 Earth Resources Technology Satellite (ERTS-1).

Statement of the Problem

The development of ADP techniques, and their application to the inventory of natural resources, have been of increasing interest during the last five to seven years. However, prior to the initiation of this study, little work had been done concerning the potential of these techniques to forest cover mapping. Consequently, answers were needed for several questions in regard to this type of application.

The first question concerns one of the advantages of the scanner over photographic systems, its ability to sense in a large number of discrete wavelength bands or "channels" (the MSS data used in this study, for instance, was acquired in twelve channels). Experience has shown that (for reasons which will be explained in the Review of Literature) it is usually not necessary nor even desirable to use all twelve of these channels to perform a classification task. Therefore, the first question involved in this study could be stated as follows: "What is the optimum number of channels to use in automatically mapping forest cover with MSS data?"

Secondly, since the small amount of work done in the past has often met with limited success, the question arises: "What is the current capability to map forest cover with MSS data and ADP techniques?"

A third question deals with one of the greatest advantages of multispectral scanners over photographic systems—their capability to sense in a much wider range of wavelength bands. The question arising from this is:

"Which of the available spectral regions (visible, near infrared, middle infrared, and thermal infrared), are the most valuable for forest cover mapping?"

Finally, the major advantage of scanner data over photographic data involves the quantitative format of the scanner data, (as compared to the more qualitative format

of photographic data). However, the capability exists to put photographic imagery into a format compatible with ADP techniques (this digitization process will be briefly described in the Review of Literature). The question to be answered here is: "How does digitized color infrared photography compare with MSS data for forest cover mapping, when using ADP techniques?"

Objectives

- 1. Determine the optimum number of wavelength bands (or channels) to use in forest cover mapping with multi-spectral scanner data and automatic data processing techniques.
- 2. Evaluate the current capability to map forest cover using twelve-channel multispectral scanner data and automatic data processing techniques. This evaluation has two specific sub-objectives:
 - a. Evaluate the current capability to automatically differentiate between forest and other cover types.
 - b. Evaluate the current capability to automatically differentiate and map deciduous and coniferous forest cover.
- 3. Determine the relative value of the spectral regions available in the multispectral scanner data (e.g. visible $[0.40-0.72~\mu\text{m}]$, near infrared $[0.72-1.4~\mu\text{m}]$, middle infrared $[1.4-4.0~\mu\text{m}]$, and thermal infrared $[4.0-13.5\mu\text{m}]$) for basic forest cover mapping.

4. Compare digitized color infrared photography with multispectral scanner data for forest cover mapping, using automatic data processing techniques.

CHAPTER II

REVIEW OF LITERATURE

Introductory Statement

The amount of literature concerning the problems to be dealt with in this study is meager. Although remote sensing devices are adequately described in the literature, these descriptions are necessary only to provide a general understanding of the nature and origin of the data. The automatic analysis of remote sensing data is only in its infancy. Research in this field is currently being conducted at only a few locations, with the Laboratory for Applications of Remote Sensing (LARS) at Purdue University widely recognized as the leader in this type of research. Much of the literature reviewed has LARS as its origin, because this study involved the particular analysis approach developed by LARS and utilized the LARS hardware and software system.

This chapter will begin with a brief discussion of photographic and multispectral scanner systems and the data which they procure, followed by a description of the data analysis sequence.

Remote Sensing Systems

Photographic

There are many types of remote sensing systems available. Photographic systems are the most common and highly developed, however. Their advantages include minimal maintenance, relative ease of operation, a familiar data format, good spatial resolution, relatively low cost for data acquisition, and the potential for three-dimensional (stereoscopic) analysis. The primary disadvantage is the limited spectral range (.4-.9 µm, approximately) of currently available photographic emulsions (Hoffer, 1971).

Cameras are so familiar that a description of their function is unnecessary. A brief description of the photographic data used in this study, however, is in order.

Kodak Aerochrome 2443 infrared film is a false color film similar to ordinary normal color films in that it has three separate emulsion layers each sensitive to a different wavelength band and each forming its own unique dye when processed. Whereas the three emulsion layers of normal color film are sensitive to blue, green, and red light, the emulsion layers of properly filtered color infrared film are sensitive to green, red, and near infrared wavelengths. A yellow filter, which absorbs blue light, is always placed over the lens because all three emulsion layers are sensitive to blue light. When the exposed film is properly processed the green-sensitive layer is developed

to a yellow positive image, the red-sensitive layer to a magenta positive image, and the near infrared sensitive layer to a cyan positive image. In the final product, then, an object which reflects only green light would appear blue, an object reflecting only red light would appear green, and an object reflecting only near infrared wavelengths would appear red (Eastman Kodak Company, 1970). In nature, objects reflect varying amounts of all three, so the rendition on the positive photograph will be some combination of all three dye layers.

Color infrared film is particularly applicable to forestry work. While deciduous and coniferous trees appear only slightly different in the visible, generally speaking, the difference between the two is usually much more pronounced in the near infrared. Because of the relatively higher infrared response of the deciduous foliage, healthy deciduous trees photograph magenta or red during the spring and summer while healthy conifers appear bluish purple (note the two triangle-shaped stands of conifers amid the deciduous forest in the northern portion of Seg. 218, Figure 25). Dead or dying deciduous or conifer foliage usually photographs as some shade of green because of the changes in infrared and visible reflectance from the senescing vegetation (American Society of Photogrammetry, 1968).

One of the objectives of this study was to compare results obtained from scanner data with those obtained from photography. This necessitated the quantization of the photography, so that it would be in a format which could be analyzed with a digital computer. The first step in this process involves the photographic separation of the three emulsion layers into positive black & white transparencies. This is accomplished by exposing black & white film to white light projected through the color infrared transparency and each of three filters (No. 49 blue, No. 60 green, and No. 25 red) (Hoffer et al., 1972). The result is three black & white transparencies representing the reflectance characteristics of the scene in the green, red, and near infrared wavelengths, respectively. Figures 21 and 23 give some idea of the appearance of the three separations.

The separations are then individually quantized by obtaining density measurements with a scanning microdensitometer. This instrument uses a light source and an optical system to project a beam through a minute portion of the film. A photoelectric sensor measures the amount of light transmitted through the film creating an electrical signal which is then converted to a digital density measurement and recorded on magnetic tape. The light source is scanned across the film, measuring its density along many small adjacent lines in sequence, thus allowing the accurate

transformation of the film density to a digital data format (Hoffer et al., 1972). With the completion of this process, the photography is in a format compatible with a digital computer.

After all three separations have been scanned, the digitized data is spatially registered or overlayed such that any given ground point in the scene coincides in all three channels of data. This is a simple task in the case of multiemulsion photography because there are no spatial distortions or inconsistencies between the three emulsion layers.

Each scan line is numbered consecutively, as is each column of samples along the scan lines, producing a coordinate system by which any point(s) in the data may be accurately designated for further study. Thus, with the three channels stored in coincidence (spatially registered) a given set of coordinates will describe the identical point(s) in each of the three channels (Hoffer et al., 1972)

Multispectral Scanner

Another type of remote sensing instrument is the multi-spectral scanner (MSS). It has several advantages over photographic systems, including the capability to sense over a much greater spectral range (0.46-11.70 µm for the scanner concerned in this study), and superior spectral resolution (the scanner senses in many narrow wavelength bands as opposed to a few broad bands). In addition, MSS data is

acquired in a format compatible with computerized analysis techniques, and it possesses the potential for accurate calibration. However, scanner imagery lacks the potential for stereoscopic analysis and the spatial resolution is generally inferior to photographic films (Hoffer, 1971).

The multispectral scanner has been in existence for some time, but its use could not be considered commonplace until the launch of ERTS in the summer of 1972. Because of the relative newness and sophistication of multispectral scanner systems, a brief description of the operation of the University of Michigan scanner (which collected the data utilized in this study) is necessary so that the reader may appreciate and understand the characteristics of the data used in this study.

As the MSS platform passes over the target, a rotating mirror scans the ground along a swath perpendicular to the flight path of the instrument. The forward motion of the platform causes the mirror to view successive, overlapping strips along the flightline (the degree of overlap of these strips is governed by the configuration of the instrument, and the altitude and ground speed of the platform). The electromagnetic energy reflected and emitted from the target is reflected off the rotating mirror, through a system of optics and into a prism spectrometer which refracts or separates the energy into the various portions of the spectrum.

Fiber optics located at appropriate points intercept the refracted spectral bands and direct the energy to sensitive detecting devices where it is measured in each of twelve channels ranging in wavelength from 0.46 µm in the visible to 11.70 µm in the thermal infrared. The level of response is then fed to a multitrack tape recorder where each of the twelve channels is recorded simultaneously in an analog format on magnetic tape (Smedes et al., 1970). effect the energy from a specific ground resolution element at a given instant in time is measured and recorded simultaneoulsy in twelve wavelngth bands, thus providing a vector, or "spectral signature" which contains spectral information available about that area on the ground (Hoffer, 1972; Landgrebe and Phillips, 1967). Obviously, there are many other types of multispectral scanner systems which can vary in many ways. The ERTS scanner, for example, has only four wavelength bands, which have a range of 0.5 µm to 1.1 µm wavelength.

The analog data tapes obtained by the University of Michigan scanner system are not compatible with digital computers, so in the analysis sequence developed at LARS, the analog tapes are put through an analog-to-digital processor which reformats the data and rewrites it in digital form on magnetic tape. During this process a number is assigned to each successive scan line of data and a sample designation to each sample point along the scan line. This provides

an X, Y coordinate system which allows the accurate designation of any point(s) in the data (Hoffer, 1972). In addition, all channels must be spatially registered or overlayed and stored in coincidence on the data tape. With these operations completed any set of coordinates which the investigator specifies will designate precisely the identical point(s) in all twelve channels of data (Hoffer, 1972). Thus, the investigator is enabled to interface with the data and analyze the spectral characteristics (reflectance and emittance) of a specific ground area using one or more of the twelve available channels.

Automatic Analysis Sequence

Introduction

Since the launch of ERTS, it has become increasingly obvious that the capability exists for collecting enormous quantities of data over large geographic areas in a very short time. Indeed, the problem of data collection seems less difficult than that of reducing the huge amounts of data to useful information (Hoffer, 1971).

Image analysis has traditionally been a manual operation. The photointerpreter plays a very important role in almost all disciplines which deal with the earth's surface. With the rapidly growing capacity for data acquisition and the increasing need for timely information from these data, however, the photointerpreter cannot hope to do the entire job alone.

The human interpreter will never be eliminated. Even with the inevitable advances in computer technology there will always be the need for high-level decisions beyond the capability of machines. However, machines do have the capability to assist the human interpreter by making many lower level decisions very rapidly.

One such automatic data processing technique developed at the Laboratory for Applications of Remote Sensing (LARS) at Purdue University involves the use of digital computers and pattern recognition algorithms in the analysis of aircraft and spacecraft multispectral scanner (MSS) data and digitized photographic imagery (Hoffer, 1972). It should be pointed out immediately, however, that the term "automatic data processing" is somewhat misleading in that there is a definite need for human interaction in all phases of the analysis sequence. Perhaps "computer-aided analysis" would be a more correct term (Hoffer, 1972).

The ADP technique developed at LARS is basically a process of selecting areas in the data where cover type and ground conditions at the time of flight are known, and designating these areas to the computer. After a set of statistical parameters have been determined for these "training samples" a pattern recognition algorithm is "trained" accordingly, and allowed to classify each unknown data point into one of the ground cover classes which it has been trained to recognize (Hoffer, 1971).

Before continuing with a more detailed discussion of the analysis sequence, however, a brief explanation of the term "pattern recognition" is necessary. Automatic pattern recognition involves the use of a machine to recognize patterns exhibited by the amplitude of the spectral response of a subject in a number of wavelength bands or "features." The digitized color infrared photography, then, contains three features and the MSS data contains twelve features.

Pattern recognition consists of two basic operations. The first is that of "training" the machine to recognize the ground cover categories of interest on the basis of their spectral response characteristics. This training procedure is explained below in greater detail. The second step consists of automatically categorizing the unknown data points on the basis of measurements derived from the selected set of features (Cardillo and Landgrebe, 1966). These measurements are the spectral responses of the ground cover types as recorded in the selected set of channels. A further discussion of the classifier programs will also follow.

The software for the actual analysis sequence may be divided into four sections: 1) statistical analysis; 2) channel or "feature" selection; 3) classification or "categorization", and 4) results display (Hoffer, 1972). These four phases are generally accomplished in the order presented, although repetition of one or more is usually necessary.

Statistical Analysis

The first step in the analysis sequence involves the selection of data samples from which the computer may derive the necessary statistical parameters for "training" the classification algorithm. Basically there are two types of categories which the computer may be trained to recognize: 1) economic or informational; and 2) spectral (Hoffer, 1972).

Since the separation of categories, by the classification algorithm, is based on spectral differences, and since categories of informational value may not necessarily be spectrally separable, it follows that for satisfactory results to be produced by these techniques, a category must be both spectrally and informationally separable. This rationale has led to two basic approaches in the selection of training samples (Hoffer, 1972).

The first approach involves the manual selection of training samples on the basis of "ground truth" information. In other words, the categories are defined on the basis of informational separability (Hoffer, 1972) (Figure 1). At this point, however, the investigator does not know if the designated informational categories are spectrally separable.

The researcher has two media by which he may manually select data samples. By requesting a line printer display of the data in one or more channels the researcher obtains an alphanumeric printout in each channel requested. These

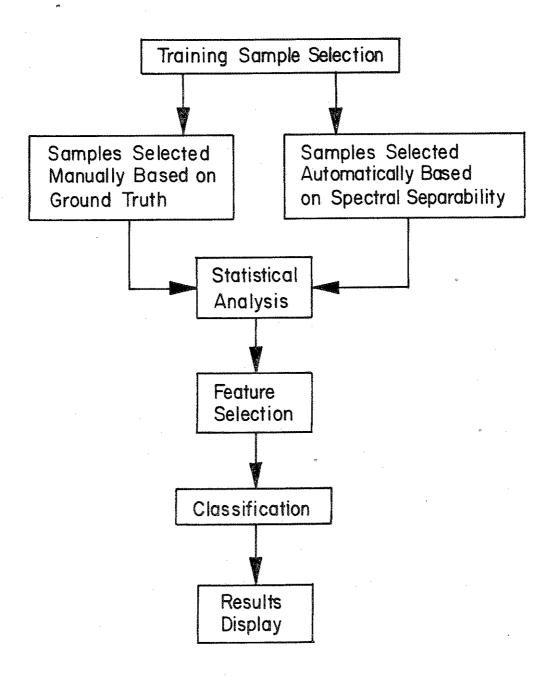


Figure 1. LARS automatic analysis sequence.

displays simulate the analog video display by dividing the continuous gray scale into discrete gray levels with an approximately equal number of points represented by each. An alphanumeric character is assigned to represent each gray level so that the relative visual density of the character corresponds approximately to the relative density of the gray level (i.e. M is assigned to the lowest gray level and a blank to the highest gray level). These characters are then printed out producing a gray level image of the data with numerical line and column designations along the edges. The researcher may then designate rectangular areas in the data by simply specifying line and column coordinates (Smedes et al., 1970; Hoffer, 1972).

Alternatively, the data may be displayed, one channel at a time, through the use of a digital display unit which presents an image in sixteen gray levels on a cathode ray tube (Figures 20, 21, 22, and 23). An attached light pen allows the researcher to outline rectangular data samples directly on the viewing screen with the so designated X, Y coordinates automatically punched on computer cards for later use (Hoffer, 1972).

In the second approach to training sample selection, the categories are defined according to spectral separability. In this approach the investigator designates an area in the data to the computer, and specifies the number of spectrally homogeneous "clusters" into which the data is to

be divided. The number of clusters requested is arbitrary, and depends largely on the investigator's knowledge of the spectral characteristics of the data set in question. The computer then assigns the individual data points to the various spectral clusters, and prints out a "spectral cluster map." It then remains for the investigator to determine the identity or informational significance of each spectral class. Usually, the researcher will also request the machine to punch a deck of coordinate cards designating sample areas which represent each of the spectral clusters or classes. These automatically designated areas of homogeneous spectral characteristics may then be used as training samples.

Experience gained at LARS indicates the desirability of using both approaches together in a procedure where the clustering algorithm assists the investigator to spectrally refine manually selected training samples.

After training samples have been selected, whether manually (from line printer displays or the digital display unit), or automatically (by the clustering program), they are submitted to a statistics processor (Figure 1). This program calculates a set of statistical parameters for each class or category represented by training samples. The parameters are based on an assumed Gaussian distribution and

include the mean, standard deviation, covariance, and divergence (a statistical measure of the separability of classes) (Smedes et al., 1970). These values constitute a statistical "fingerprint" for each class or category of ground cover, and will be used later as a basis for both feature selection and categorization of unknown data points (Smedes et al., 1970).

The statistics processor may be requested to provide a number of different types of output useful in the analysis sequence. Histograms of individual training fields or of groups of fields which have been designated a class (Figure 2) give the researcher an idea of the distribution of the data points in the various channels (Hoffer, 1972).

Coincident spectral plots (Figures 3 and 4) illustrate the relative amplitude of the spectral responses of the various classes in each of the individual wavelength bands or channels. The mean spectral response, plus or minus one standard deviation, is presented as a line of representative length. The researcher may thus obtain some indication of the statistical quality of the data (high or low variance) (Hoffer, 1972), and of particular importance, an indication of the spectral separability of the ground cover classes in the various wavelength bands. This capability has proven its value in helping researchers to better understand the relative spectral characteristics of the various ground cover types involved.

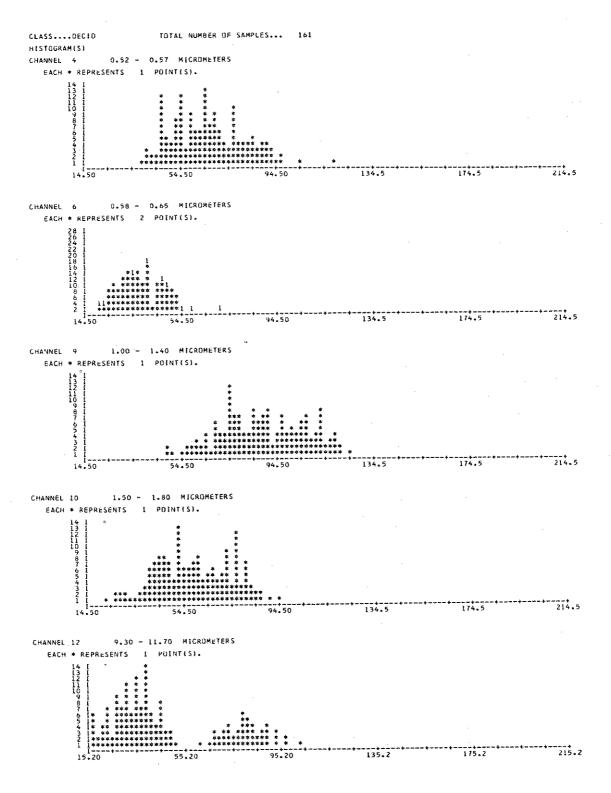


Figure 2. Training class histograms for deciduous forest: channels 4, 6, 9, 10, and 12.

Figure 3

Coincident spectral plot of training field statistics for 12-channel MSS data.



of four channels. The feature selection processor is designed to give the researcher some idea as to which of these combinations is the best.

Based on the punched output generated by the statistics processor, the feature selection program calculates the separability between all possible pair-wise combinations of cover type classes (as defined by the training deck) for all possible combinations of four channels (or any other number of channels from one to eleven). The processor then ranks the channel combinations.

There are three options, however, by which the researcher may influence the order of ranking. One option provides for the application of differential interclass weighting to one or more combinations of cover type classes. For example, if it was of particular importance to separate "forest" from all other classes, the researcher could simply attach a greater weight or importance to the interclass divergence (statistical measure of distance between classes) of all pair-wise combinations containing the class FOREST. Likewise, if it were of no importance to separate two classes of corn, a weight of zero might be applied such that the processor would disregard the interclass divergence between Thus, a channel combination with little the two classes. or no ability to accurately separate the two would not have its chances of selection reduced as a result.

A second option by which the researcher may influence the ranking of the channel combinations involves a choice between two simple ranking criteria: "average divergence" and "minimum divergence". If average divergence is requested, the processor calculates the average interclass divergence (weighted or unweighted) for all pair-wise combinations of cover type classes. The channel combination offering the highest average interclass divergence is then ranked first.

Minimum divergence, on the other hand, determines the lowest interclass divergence for each and every channel combination. That combination possessing the highest minimum interclass divergence is then ranked first. It is not uncommon for the same channel combination to exhibit both the highest average and the highest minimum divergence.

A third method of influencing channel selection is to simply delete selected channels from consideration by the processor. All three of these options will be discussed further in the chapter on Materials and Procedures.

The whole idea of the feature selection processor, of course, is to assist the researcher in selecting the "best" channel combination. Keep in mind, however, that feature selection is based on statistics derived from samples of the data set to be classified. Since a sample can never

be completely representative of the whole, the selected channel combination, though it may be "best" for separating the classes as represented by the training samples, may not necessarily be the "best" for classifying the data as a whole. The highest ranking channel combination according to the feature selection processor, then, is only an approximation.

Classification

The third phase of the analysis sequence involves the classification of the unknown data points (Figure 1).

Currently there are two different statistical pattern recognition algorithms in use at LARS for this purpose.

The first and most commonly used is a "perpoint" classifier (classifies data points individually) which requires, as input, the statistics deck, the selected combination of channels, and the coordinates of the area(s) which the researcher wishes the machine to classify. Based on the statistical definitions of the cover classes in each of the selected channels, the machine establishes decision boundaries in N-dimensional space (N = the number of channels used in the classification), then individually assigns the unknown data points to one of the statistically defined classes on a maximum likelihood basis. The results are then recorded on magnetic tape for later display (Hoffer, 1972).

The second is a "perfield" or "per sample" classifier, which, instead of classifying data points individually, classifies entire fields of data points as individual decisions (Anuta et al., 1971). In addition to the statistics deck and the selected channel combination, the researcher is required to submit field coordinates designating samples of known cover type to be classified. The program then classifies each field into one of the cover type classes which it has been trained to recognize, and prints out a table of quantitative results (Table 14 and 15).

The perfield classifier has the advantage of greater speed, hence the consumption of less computer time. In addition, the perfield classifier makes some use of spatial data by considering an entire group or field of data points individually. Thus, if two hypothetical classes possessed similar mean responses, but significantly differing standard deviations in the channels selected for the classification task, the perpoint classifier, by considering data points individually, would likely result in considerable confusion.

The principal disadvantages of the perfield classifier include its inability to establish field boundaries, hence the necessity for the researcher to perform this task in advance. Also, unlike the perpoint classifier, the classification results may not be displayed in a map-like image.

Results Display

With the perpoint classification completed and recorded on magnetic tape, the results may be displayed both quantitatively, in a tabular format, and qualitatively, as a map or image.

The quantitative results display consists of a listing, by class, of all training fields and a tabulation of the number of points in each field classified into each class. This is followed by a summarization of training class performance similar to Tables 5-11.

In order to obtain a more meaningful evaluation of the classification, however, the researcher will have selected "test fields" (samples not used in training, but of known cover type) before the classification was run (to minimize bias). These test fields are then examined by the results display program which determines how well the classifier performed on these areas. The results are then displayed in the same format as decribed above (Smedes et al., 1970) (Tables 5-11 are examples of test class performance tables).

A rejection or "threshold" capability may be used in the display program. By specifying an arbitrary threshold level, the researcher directs the computer to decline final classification of data points which do not look sufficiently like the class to which they have been tentatively assigned. Even though the tentative assignment is to the "most likely" class, these borderline points are placed

in a null category prior to the calculation of test results (Smedes et al., 1970). The implications of thresholding will be discussed briefly in the chapter on Materials and Procedures.

Qualitative or map-like displays of classification results may be obtained in one of two forms. First is the alphanumeric line printer display which is very similar to that described earlier in this chapter. The principal difference is that the researcher is required to choose characters to represent the various classes. If desired, such a line printer image may be manually color coded, but this is a time consuming process.

A second and more efficient means of obtaining color coded classification results is by use of the digital display unit, also mentioned earlier. The researcher specifies colors to represent the various classes, and the machine determines the proper gray levels for each of three images which are then displayed one at a time. An attached photographic unit allows the researcher to obtain a multiple exposure, on color film, of the three gray scales, each through a different filter (blue, green, and red). The result is a color composite of the classification results (Figures 26 and 27).

Experience gained at LARS indicates that the initial classification attempt will often fall short of the investigator's objectives. If the unsatisfactory performance is

a result of incorrect or inadequate training statistics then the researcher must go through a process of refining his training fields and classes to a point where the test results indicate the true capability to automatically classify the data. By examining output from the various programs, especially the statistics processor and the quantitative results from the display program, the training deck is revised and the sequence repeated. The human element is obviously far from eliminated.

CHAPTER III

MATERIALS AND PROCEDURES

Introductory Statement

The procedures described in this section are adaptations of those in the standard LARS analysis sequence outlined in the Review of Literature. Data input includes multispectral scanner (MSS) imagery, color infrared (CIR) imagery (in both photographic and digital formats), and surface observations. Specific data used are on file in the LARS data library.

Test Site Description

A 1 x 10 mile strip of land in Indiana, designated as Segment 218, was the test site for this research. The site, which has a north-south orientation, is located in Owen County, about 2 1/2 miles west of Spencer, and about 45 miles southwest of Indianapolis. The site is located on the Crawford Upland, a maturely dissected, westward sloping plateau characterized by abundant stream valleys and a

well-integrated drainage system. Most of the land area is "in slope," with flat, narrow ridge tops and steep valley walls (Schneider, 1966).

Because of the extensive dissection of the terrain, most of the agricultural land is in pasture and hay. Where the topography allows, however, row crops (corn and soybeans) are present, particularly on the floodplain of the White River (Figure 23).

A dot grid count on 1:120,000 scale color infrared photography reveals about 60 percent of the area to be forested. Most of this forest is composed of natural hardwoods, (primarily tulip poplar, oak, hickory, maple, and ash), though a few small white pine stands are present in the segment. These are presumably plantations on abandoned agricultural lands dating from the Civilian Conservation Corps (CCC) days of the mid 1930's.

Much of the forested area has been grazed by domestic livestock for many years. As a result, many of the forest stands are open and park-like with a low stem density and very incomplete crown closure. The increased illumination of the forest floor allowed by this condition has resulted in an invasion by grass. In short, much of the so-called forested area is, in reality, an intimate mixture of forest and pasture.

Data Utilized

Multispectral Scanner Data

The multispectral scanner data used was collected by the University of Michigan/Willow Run Laboratories with a twelve-channel, single-aperture scanner. The instrument, mounted in a C-47 aircraft, was flown at an altitude of 5,000 feet above terrain and the data utilized was obtained on August 12, 1971 at 1504 Greenwich Mean Time (about 0917 local solar time). This meant that the data had to be sun-angle corrected before it could be used successfully.

The data, was recorded in twelve wavelength bands in an analog format as follows:

<u>Channel</u>	Wavelength Band (µm)	Spectral Region
1	0.46-0.49	visible
2	0.48-0.51	visible
3	0.50-0.54	visible
4	0.52-0.57	visible
5	0.54-0.60	visible
6	0.58-0.65	visible
7	0.61-0.70	visible
8	0.72-0.92	near infrared
9	1.00-1.40	near infrared
10	1.50-1.80	middle infrared
11	2.00-2.60	middle infrared
12	9.30-11.70	thermal infrared

However, analog data is not compatible with a digital computer, so an analog-to-digital processor was necessary in order to convert the data to a format which LARS' IBM 360/67 computer could handle. The digitized channels were next overlaid (registered), and a line and column coordinate system added, to allow the researcher to interface with the data. This data was then designated as Run Number 71052501.

Photographic Data

The photographic data was acquired on Kodak Aerochrome Infrared 2443 film in a 9 1/2 inch format. The aerial photos were acquired by the National Aeronautics and Space Administration using a Wild RC-8 mapping camera equipped with a Wild .510 µm cut-off (minus blue) filter. The camera (with six-inch focal length lens) was mounted in a United States Air Force RB-57F reconnaissance aircraft flown at an altitude of 60,000 feet above terrain. This elicited imagery in a contact scale of 1:120,000. The specific photographic frame used in this research project was exposed on August 12, 1971 at 1526 GMT (about 0939 local solar time), only 22 minutes after the MSS data was acquired (frame number 0076 of NASA Mission 177).

Data in a photographic format is not compatible with a digital computer, so the three emulsion layers had to be photographically separated and individually digitized, as described in the Review of Literature. The digitized data was then designated as "Run Number 71056903". The sensitivities of the photographic emulsion layers provided three channels of data as follows:

<u>Channel</u>	Wavelength Band (µm)	Spectral Region
1	0.47-0.61	visible
2	0.59-0.71	visible
3	0.68-0.89	near infrared

The photography also served as a valuable secondary source of "ground truth", particularly in cases where there were any questions concerning the primary surface observation data.

Surface Observation Data

In May 1971, all farm operators in test Segment 218
were interviewed by agents from local offices of the
Agricultural Stabilization and Conservation Service (ASCS).
These interviews were performed as part of the "1971 Corn
Blight Watch Experiment," which also provided the imagery
used in this experiment.

The interviews yielded data on the crop type or land use of each individual field in the entire test segment.

This information formed the primary basis for the selection of training and test fields used in this investigation.

However, these data had to be used with discretion, and with a knowledge of agricultural practices in the area.

For instance, fields observed in May and listed as containing wheat had been harvested before August (the time of aerial data collection). Other fields, described as pasture, or simply as woods, were often grazed woodlots. Other apparent discrepancies were a function of the agricultural practices involved. A field observed as corn might be so weedy as to bear little spectral resemblance to more normal corn fields. It was in such questionable instances

that the color infrared photography was used to either verify or correct the surface observation data.

Special Data Analysis Techniques

The basic analysis procedure has already been described in the Review of Literature and diagrammed in Figure 1.

Briefly, the first step was to develop a set of fields and classes which could be used to train the computer to spectrally identify the categories of interest. Secondly, in order to obtain a quantitative determination of the accuracy with which the computer performed, it was necessary to select a set of test areas that was both representative and comprehensive. However, before the analysis could begin it was necessary to establish a few rules.

Objective 1 called for a determination of the optimum number of channels to use in mapping forest cover. One would expect the best accuracy to be obtained when using all available channels and, in fact, this usually is the case. However, an increase in the number of channels used in a classification requires a disproportionate increase in computer time (Figure 5), which costs on the order of \$250 per hour and brings to bear the obvious action of the law of diminishing returns on classification accuracy. One might conclude that, considering the dual parameters of both accuracy and cost, something less than all twelve channels might be optimum. Indeed, experience has shown that

the right combination of four or five channels gives almost the same accuracy as obtained with all channels, and at a far lower cost in terms of computer time.

The optimum channel number study outlined in Objective 1, however, requires the prior development of representative training and test decks to be used as standards throughout. This, in turn, requires a decision as to how many channels should be used during the development of these decks. Therefore, based on past experience and the intuitive feeling developed by the more experienced researchers at LARS, the decision was made to use four channels in the initial development of the training and test decks.

After deciding how many channels to use, it became necessary to decide just how the "best" combination of channels would be selected. As mentioned in the Review of Literature, the separability processor offers the researcher three basic options by which he may influence the computer's selection of the "best" channel combination. The processor may first be requested to select the optimum combination of channels on the basis of either the highest average interclass divergence or highest minimum interclass divergence. Since preliminary studies indicated that deciduous forest and coniferous forest, the two classes of primary concern, would be the most difficult pair of classes to separate, it was decided to select the "best" channel combination on the basis of highest minimum interclass divergence.

Another option in the separability processor allows the researcher to differentially weight one or more pairs of classes. From this, one immediately realizes that within this option, the number of possible ways to influence the selection of the "best" channel combination is limitless. Therefore, in order to keep the analysis following a well-defined procedural path, it was decided to use no differential interclass weighting with the separability processor.

The third option available for influencing channel selection is that of simply deleting one or more channels from consideration by the processor. This option was not used in the development of the standard training and test decks.

Another decision that had to be made was one concerning the use of thresholding in the calculation of classification results. The classifier algorithm is designed to classify each and every point into the class it most nearly resembles, even though the resemblance may be quite remote. Some points, therefore, will be borderline and of doubtful identity. For this reason a thresholding option was incorporated into the display program in which classification performance figures are calculated. The thresholding option simply places borderline points into a separate null or "threshold" class, which would be very useful if it affected only misclassified points; however, it will also threshold weakly (but correctly) classified points. The final result

is that classification accuracies cannot be <u>increased</u> by thresholding and, in fact, they are nearly always <u>reduced</u> somewhat. Because of this bias, which may affect different classes in different ways, thresholding was not used in the calculation of any quantitative test results.

With the establishment of rules regarding the number of channels to use initially, the selection of the "best" channel combination, and thresholding, the analysis procedure was followed as outlined in the Review of Literature.

The accuracy of the first classification attempt was quite poor. A careful analysis of the color infrared photo revealed the probable cause to be several questionable designations in the ASCS ground observations.

It was evident, upon careful examination of the photography, that the computer had, in some instances, been trained incorrectly to identify certain cover types, and had then been asked to identify test areas as something which they were not.

The most common discrepancies involved training and test fields designated as either deciduous forest or forage when in fact they were some of both; that is, they were grazed woodlots with very low stand densities in which portions of the fields were pasture (grass) while other areas of the same field consisted of tree foilage. To train the computer to recognize the entire field as either pasture or trees would have certainly been incorrect. Likewise, it

would have been unfair to expect the machine to classify such a test area as either one or the other. Such fields, therefore, had to be deleted from consideration as training or test areas.

A similar problem occurred in several fields which were "corn", according to the surface observation data. The farmers concerned had apparently made little or no effort at weed control. Again, it would have been incorrect to train the computer to recognize such a field as corn when its spectral response was due largely to the presence of weeds. Such anomalous fields were therefore deleted.

For the most part, the ASCS ground observation data was adequate for training and test field selection. However it had been collected three months before the acquisition of the MSS and photographic imagery used in this research project and was intended for use in an agricultural survey. Thus, in addition to some of the observations being out-of-date, the land use definitions utilized were agriculturally oriented and often inadequate for application to forest cover classification. Consequently, apparent discrepancies had to be resolved on the basis of careful interpretation of the color infrared photography. The training and test decks were then appropriately corrected. The analysis procedure was next repeated in its entirety, in order to refine the training deck.

During this procedure, an attempt was made to select test areas in approximately the same proportions as represented by the various cover classes in the segment. While this was not necessary to obtain reliable figures for the classification accuracies of individual classes, it did make possible a more reliable estimate of the classification performance of the segment overall. The training sample selection process was long, subjective and certainly not "automatic" or operational, but it was necessary in order to develop adequate training and test decks to be used as standards in subsequent experiments (Appendix A).

Channel Number Study

As stated previously, during much of the past analysis of MSS data at LARS, four channels have customarily been used for the classification of the data. Though the use of more channels increases accuracy somewhat, it also drastically increases the amount of computer time (and thus the cost). The use of four channels, then, has generally been considered the best trade-off between classification accuracy and computer time. This practice has been based largely on intuition, however, since there have been no formal studies conducted using data acquired by the multi-spectral scanner in its current configuration.

Therefore, before proceeding with the rest of this research, it was decided to run a simple experiment to see

whether or not four channels seemed optimum. The computer was given the statistics derived from the final training deck, and the separability processor was requested to select the best 1, 2, 3, 4, 5, 6, 8 and 10 channels, according to minimum divergence, and without weighting. The flightline was then classified with each of the best n-channel combinations and with all twelve channels. The resulting test class accuracies, along with computer time required, were plotted over number of channels used (Appendix B, Figure 5). Based on these results, the decision was made to use five channels in all subsequent work. The decision was arbitrary, however, in the sense that a detailed cost-benefit study was beyond the scope of this project.

Forest Mapping Capability

To determine the "absolute" capability to map forest cover with MSS data and ADP techniques is impossible. No matter how much time and effort one might devote to refining the training deck, there would always be room for improvement.

However, in order to arrive at an approximation of what might be expected, the results of two classifications were studied. Since it had been previously decided that the use of five channels offered the best trade-off between computer time and accuracy, the results of the classification performed by the best five-channel combination were studied further.

This five-channel classification offered what might be expected in an "operational" situation, assuming of course, that five channels would be used in such a situation. One must fully recognize, of course, that advances in computer technology may make it quite feasible to use all available channels. As a comparison, therefore, the results obtained by the use of all twelve channels were also examined, even though the slight gain in classification accuracy was at the expense of a considerable amount of computer time.

Another consideration is that the second objective of this study requires a determination of the capability to differentiate between general forest cover and other cover types, as well as the capability to distinguish deciduous from coniferous forest. In the classification of the data, deciduous and coniferous forest were treated as separate classes, therefore the results did not give an accurate idea of how well forest cover, in general, could be classified. To remedy this situation, the test class results from deciduous forest and coniferous forest were mathematically combined to form a separate class. effect, a test point from either of the two forest categories was considered to be correctly classified if it was classified as either deciduous or coniferous forest. Confusion between the two forest categories, then, was not considered in computing the accuracy for the "combined

forest" category. As an example consider Table 3 and Figure 8 in which [(29745 + 1001 + 3 + 85)/(32252 + 88)] x 100 = 95.4% is the classification accuracy for combined forest. The figures for overall classification accuracy, however, were calculated by the computer with deciduous and coniferous forest considered as separate categories.

Spectral Region Evaluation

For the purposes of this study, the twelve available channels of scanner data may be grouped into four basic regions of the electromagnetic spectrum — visible, near infrared, middle infrared, and thermal infrared (Figure 6). These spectral regions seem to vary in importance or value as far as the classification of scanner data is concerned. Because of this, it was decided to use the final training and test decks to draw some general conclusions as to the relative values of these spectral regions.

The statistics derived from the training deck were submitted to the separability processor as before, except that all the channels comprising a given spectral region were deleted from consideration in various combinations of one or more spectral regions at a time. The processor, then, was required to select the best combination of five channels from the spectral region or regions which had not been deleted. In one iteration, for instance, all infrared channels were deleted, thus requiring the processor to select from the visible channels only. In another iteration,



MSS-Digitized CIR Comparison

Several approaches were tried in order to achieve a comparison between the automatic forest cover mapping capabilities using scanner imagery and digitized color infrared (CIR) photography. The first step, however, was to obtain a line printer display of the digitized photography and carefully determine the coordinates of training and test fields exactly corresponding to those used in the analysis of the scanner imagery. Thus the computer was trained and tested with the same areas on both sets of data. of differences in digitization rates between the scanner data and the digitized photography, the numbers of data points were not the same, even though the areas involved were identical. It should also be noted that there were several training and test fields at the southernmost end of the segment which did not appear on the digitized photograph, but which were included in the scanner data analysis. cause the segment was too long to appear in its entirety on any one frame of photography, portions of the two adjacent frames would have had to be digitized in order to include the entire segment, adding significantly to the difficulty of the procedure.

With the transfer of training and test fields completed, the segment was classified, using all three channels of digitized photographic data, and the perpoint classifier as previously described. As a further study a "perfield"

classifier was used which, on the basis of the same set of training statistics, classified each test field as an individual decision, into one of the six defined classes.

The results from these two classifications were then compared with similar classifications of the MSS data. Since MSS Channels 4, 7, and 8 correspond approximately to the three available channels of the digitized color infrared photography (Figure 7), classification results using these three MSS channels were utilized for the comparisons.

In the process of evaluating the results from this study, a visual comparison of the two sets of data (MSS and digitized CIR photography) was desired. Gray scale images of the corresponding channels (MSS Channels 4, 7, and 8, and CIR Channels 1, 2, and 3) were photographed from the digital display unit (Figures 20-23). In addition, color infrared reconstitutions of the two sets of data were produced by a process similar to that described in the Review of Literature for the production of color-coded classification results.

Basically, this procedure consists of displaying the three channels in each data set as described in the paragraph above. Instead of obtaining black and white photographs of the individual gray scales, however, a single frame of color film is exposed successively to each of the three appropriately filtered gray scales. For example, in the digitized CIR data, Channel 1 covers the green portion

of the spectrum. Since green wavelengths produce a blue rendition on positive color infrared film, the gray scale of Channel 1 is photographed, from the digital display, through a blue filter. Channel 2, which covers the red portion of the spectrum and produces a green rendition on CIR film, is exposed through a green filter. Likewise Channel 3, covering the near infrared wavelengths, is exposed through a red filter. With all three of these filtered gray scales recorded, consecutively, on the same frame of normal color film, a color infrared reconstitution of the data is produced (Figure 25).

Channels 4, 7, and 8 of the MSS data were photographed in the same manner, thereby producing the images in Figure 24. These images of the digitized data provided a means by which the data could be visually compared.



With the cost of computer time at \$250 per hour, and the obvious action of the law of diminishing returns on the overall classification accuracy with increased number of channels, it would seem that a combination of far less than twelve channels would be optimum. Without the assistance of a detailed cost-benefit study, it was decided to use the best five-channel combinations of wavelength bands in all subsequent work as the best five-channel combination gave an overall classification accuracy slightly in excess of 90 percent and used only a little more than twenty minutes of computer time.

Forest Mapping Capability

The best five-wavelength band classification results, and the maximum accuracy classification results, (obtained by using all twelve wavelength bands) are illustrated in Figures 8 and 9 and Tables 3 and 4. (A color-coded classification of the northern and southern portions of Segment 218, using the best five-channel combination, is shown later in Figure 26).

The bars labeled "combined forest" in Figures 6 and 7 illustrate results of a mathematical combination of classification results from the deciduous and the coniferous forest categories, and indicate the separability of general forest from other cover types. This combined forest class separates accurately from all other cover types (95.3 percent with the "best" combination of five channels and

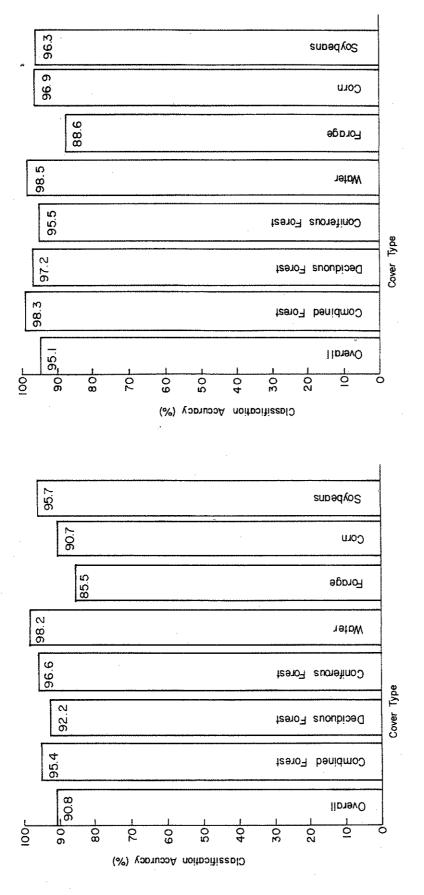


Figure 9. Test class performance of MSS data using all twelve channels.

Test class performance of MSS data using best 5-channel combination.

ထံ

Figure

Table 3. Test class performance using best combination of five channels.

CHANNELS USED

CHANNEL 4	SPECTRAL BAND	0.52 10	0.57 MICRGMETERS	CALIBRATION CODE = 1	C0 # 0.0
CHANNEL 6	SPECTRAL BAND	0.58 TO	0.65 MICROMETERS	CALIBRATION CODE # 1	0.0 = 0.0
CHANNEL 9	SPECTRAL BAND	1.00 TO	1.40 MICROMETERS	CALIBRATION CODE = 1	CO = 0.0
CHANNEL 10	SPECTRAL BAND	1.50 TO	1.80 MICROMETERS	CALIBRATION CODE = 1	CG = 0.0
CHANNEL 12	SPECTRAL BAND	9.30 TO	11.70 MICROMETERS	CALIBRATION CODE = 1	CO = 32.70

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	HATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER C	F SAMPLE	ES CLASSIF	IED INTO	
	GROUP	NO OF SAMPS	CORCT.	DECID	CONIFER	WATER	FORAGE	CORN	SOY
ì	DECID	32252	92.2	29745	1001	0	378	245	883
2	CONTFER	88	96.6	3	85	0	0	0	0
3	WATER	339	98.2	1	2	333	3	0	0
4	FORAGE	11760	85.5	22	7	2	10052	413	1264
5	CORN	2679	90.7	ı	4	0	191	2431	52
6	SOY	2676	95.7	10	0	G	91	15	2560
	TOTAL	49794		29782	1099	335	10715	3104	4759

CYERALL PERFORMANCE(45206/ 49794) = 90.8

AVERAGE PERFORMANCE BY CLASS(558.9/ 6) = 93.2

Table 4. Test class performance using all twelve channels.

						CH	ANNELS USED							
CHANNEL	1	SPECTRAL	BAND	0.46	TO	0.49	MICROMETERS	CALIBRATION	CODE	±	1	co	3 :	0.0
CHANNEL	2	SPECTRAL	BAND	0.48	TO	0.51	MICROMETERS	CALIBRATION	CODE	×	1	ÇΟ	Ξ	0.0
CHANNEL	3	SPECTRAL	BAND	0.50	TO	0.54	MICROMETERS	CALIBRATION	CODE	±	1	CO	±	0.0
CHANNEL	4	SPECTRAL	BAND	0.52	ŦΟ	0.57	MICROMETERS	CALIBRATION	CODE	=	1	ÇO	=	0.0
CHANNEL	5	SPECTRAL	BAND	0.54	TO	0.60	MICROMETERS	CALIBRATION	3000	22	1	C O	=	0.0
CHANNEL	6	SPECTRAL	BAND	0.58	10	0.65	MICROMETERS	CALIBRATION	CODE	=	i	€0	=	0.0
CHANNEL	7	SPECTRAL	BAND	0.61	ro	0.70	MICROMETERS	CALIBRATION	CODE	×	ı	εo	3.0	0.0
CHANNEL	8	SPECTRAL	BAND	0.72	TO	0.92	MICROMETERS	CALIBRATION	CODE	Ξ.	1	CO	æ	0.0
CHANNEL	9	SPECTRAL	BAND	1.00	10	1.40	MICROMETERS	CALIBRATION	CODE	=	1	C O	=	0.0
CHANNEL	10	SPECTRAL	BAND	1.50	ro	1.80	MICROMETERS	CALIBRATION	CODE	=	l	CO	#	0.0
CHANNEL	11	SPECTRAL	BAND	2.00	ŦO	2.60	MICROMETERS	CALIBRATION	CODE	=	ì	CO	=	0.0
CHANNEL	12	SPECTRAL	BAND	9.30	TO	11.70	MICROMETERS	CALIBRATION	CODE	=	ì	CO	F	32.70
							CLASSES							

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	WATER	6	SOY

					NUMBER C	F SAMPL	ES CLASSIF	LED INTO	
	GROUP	NU OF SAMPS	CORCT	DECID	CONTRER	WATER	FORAGE	CORN	50Y
1	DEC 1D	32252	97.2	31339	359	0	263	112	179
. 2	CONTEER	88	95.5	4	84	D	0	0	0
3	WATER	339	98.5	ı	1	334	3	Э	0
4	FORAGE	11760	88.6	39	5	1	10420	245	1050
5	CORN	2679	96.9	1	5	0	61	2597	16
6	SOY	2676	96.3	5	1	Û	74 .	18	2578
	TOTAL	49794		31389	452	335	10821	2972	3825

OVERALL PERFORMANCE(47352/ 49794) = 95.1 AVERAGE PERFORMANCE BY CLASS(573.0/ 6) = 95.5 98.3 percent with all twelve channels used), a result showing a potential for using ADP techniques in operational situations.

Table 3 shows that coniferous forest seems to separate quite well from the other cover types considered (about 96 percent), while deciduous forest cover offers a bit more difficulty, as shown by a classification accuracy of 92 percent. Table 3 further indicates that much of the misclassification of deciduous forest is a result of confusion with coniferous forest, as illustrated by the 1001 deciduous test points which were misclassified as coniferous forest.

An examination of Figure 26 illustrates many scattered individual points of conifer in the deciduous forest areas. These misclassified points are apparently areas of shadow in the deciduous forest canopy. These shadow areas are explained by the fact that, like most forest stands, the deciduous forest areas in this segment do not have a crown closure of 100 percent. In fact, crown closure is more on the order of 60 to 70 percent, with far less than that in many of the areas where livestock has been allowed to graze. The resulting small clearings, combined with the extremely rough texture of the uneven-aged forest canopy, create many areas of shadow which, in some cases, were confused with the darker tones of coniferous crowns (note the triangle-shaped conifer stands in the northern portion of Segment 218, Figure 24). This rough texture of the forest canopy

resulted in many areas of shadow, but it also caused highly illuminated points on the sunward side of tree crowns. This additional phenomenon seemed to account for many of the data points in deciduous forest areas which were misclassified as agricultural cover types.

It should be noted that the LARS system of determining test area accuracies often results in conservative accuracy percentages. This is because an entire test area must be declared by the researcher to be one cover type or another, rather than a mixture. However, in reality, mixture of cover types are the rule and were often mapped out by the computer as such, but in the tables of test areas, this situation is not apparent. For example, some of the deciduous forest test points "missclassified" as forage were not misclassifications at all. In grazed woodlands where the forest canopy density has decreased and the entire stand has become more open over time, grass has invaded the forest floor. In many cases the classifier, in fact, correctly classified such forage areas under open deciduous stands. Conversely, the system has correctly classified scattered individual tree crowns growing in pasture fields (compare southern portion of Segment 218 in Figure 24 with classification results in Figure 26). Therefore, in some cases, the actual classification accuracy may be even better than the numbers indicate.

The water, forage, corn and soybean classes varied considerably in their classification performance. As is usually the case, water was classified with an extremely high accuracy, due to its low reflectance in the near and middle infrared portions of the spectrum (Figure 3). The row crop categories, corn and soybeans, also were classified with quite high accuracy as a combined class. An examination of Table 3 reveals that what confusion did take place with corn and soybeans was primarily between the two categories rather than with other cover types. Forage, which is a "catch-all" category to a certain extent, since it combines pasture, hay, and stubble, had an extremely wide variance and inevitably classified rather poorly, seldom exceeding 85-88 percent accuracy.

While confusion occurred between many of the categories, it should be emphasized that the confusion between the forest categories and other non-forest categories was minimal, indicating the relatively high spectral separability of forest, in general, from other cover types, using ADP techniques. This result is one of the major, significant findings of this research.

Table 4 lists the results of the classification derived from use of all twelve channels. (These results are also illustrated in Figure 7). The overall classification performance was slightly over 95 percent and, as an individual cover type, only forage did not exceed 95 percent

accuracy. While the overall accuracy was increased by about 4 percent over the use of the best five-channel combination, the amount of computer time required to buy this increased accuracy was considerable -- about 90 minutes compared to 20 minutes as indicated in Figure 5. With computer time costing \$250 per hour, this is an increase from \$83 to \$375.

Spectral Region Evaluation

One of the major phases of this research project involved the evaluation of the spectral regions in which the scanner data was obtained, including the visible (0.46-0.72 um), near infrared (0.72-1.4 um), middle infrared (1.4-4.0 m) and thermal infrared (4.0-13.5 m). This was the first time that this type of quantitative evaluation of the various spectral regions had been conducted. 5-11 show the test class performances obtained in the various analysis sequences conducted during this phase of the research. From these tables, Figures 10-17 were prepared using the percent correct identification for the test samples of the different cover types. All cases (Tables 5-11) involve only five wavelength bands for the classification. Table 5 is the control in that all twelve wavelength bands were considered by the feature selection processor, with the resulting best five-channel combination used in the classification. In the subsequent analysis

Classification results: all channels considered. Table 5.

		CALIBRATION CODE = 1 CALIBRATION CODE = 1 CALIBRATION CODE = 1	0.00
		CALIBRATION CODE = 1 CALIBRATION CODE = 1 CALIBRATION CODE = 1	0.0 = 0.0
		CALIBRATION CODE = 1 CALIBRATION CODE = 1	0.0 = 0.0
		CALIBRATICH CODE = 1	6
			0.0
CHANNEL TO SPECIKAL BAND	AND 1.50 TO 1.80 MICROMETERS	CALIBRATION CODE # 1	0.0 = 0.0
CHANNEL 12 SPECTRAL BAND	AND 9.30 FO 11.70 MICAUMLFERS	CALIBRATICA CODE = 1	C0 = 32,70
	CLASSE		
CLASS		CLASS	
DECIDADO		4 FORAGE	
CONTFER		5 CORN	
WATER		A SOVEEN	

		1			NUMBER DI	= SAMPLE	NUMBER OF SAMPLES ULASSIFIED INTO	ED INTO	
0 32252 92.25 29745 1001 0 378 245 88 96.6 3 85 0 0 0 339 98.2 1 2 333 3 0 11760 85.5 22 7 2 10052 413 1 2679 90.7 1 4 0 191 2431 2676 95.7 10 0 91 15 2731 49794 29782 1099 335 10715 3104 4	GROUP	SAMPS	CORCT	DEC IDUUD	CUNIFER	WATER	FORAGE	CORN	SOYBEAN
88 96.6 3 85 0 0 0 0 339 98.2 1 2 333 3 0 0 11760 85.5 22 7 2 10052 413 2679 90.7 1 4 0 191 2431 2676 95.7 10 0 0 91 15 4979 29782 10999 335 10715 3104	DECIDODO	32252	92.2		1001		378	245	683
339 98.2 1 2 333 3 0 0 1 1760 85.5 22 7 2 10052 413 1 2 1760 95.7 1 2 1760 191 2431 1 1 4 0 191 2431 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	CONTFER	88	9.96	٤1	85	0	၁	0	0
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	WATER	339	98.2		2	333	٢	0	0
V 2676 95.7 10 0 0 91 15 2431 2676 95.7 10 0 0 0 91 15 2431 29794 29782 1099 335 10715 3104	FORAGE	11760		22	7	2	10052	413	1264
2676 95.7 10 0 0 91 15 49794 29782 1099 335 10715 3104	COKN	2679		-	. 4	0	161	2431	. 52
49794 29782 1099 335 10715 3104	SOY BE AN	2676	7.56	0.7	0	0	16	51	2560
	TOTAL	46164		29782	1099	335	10715	3104	4759

OVERALL PERFORMANCE(45206/ 49794) = 90.8 AVERAGE PERFORMANCE BY CLASS(558.9/ 6) = 93.2

only visible channels considered. Classification results: Table 6.

CHANNEL 1 SPECTR			CHALL A LHAMAHO					
med								
	SPECTRAL BAND	0.46 TO	0.46 TO 0.49 MICROMETERS	CAL	CALIBRATION CODE =	CODE =	0*0 = 00	0
CHANNEL 3 SPECTR	SPECTRAL BAND	0.50 TO	0.54 MICROMETERS	CAL	CALIBRATION CODE =	CODE =	0.0 = 0.0	٥
CHANNEL 4 SPECTR	SPECTRAL BAND		0.52 TO 0.57 MICROMETERS	CAL	CALIBRATION COUF =	C00E = 1	0.0 = 0.0	0
CHANNEL 5 SPECTR	AL BAND	0.54 10	SPECTRAL BAND 0.54 TO 0.60 MICROMETERS	CAL	CALIBRATION CUDE =	cube =	0*0 = 00	0
CHANNEL 6 SPECTR	SPECTRAL BAND	0.58 10	0.58 TO 0.65 MICROMETERS	CAL	CALIBRATION CODE =	CODE = 1	0*0 = 00	0
			CLASSES					
CLASS	٠				CLASS			
1 0601000		15		4	FORAGE			٠.
2 CONIFER				5	CORN			
3 WATER				9	SUYBEAN			

SOYBEAN 782 1619 83 2433 NUMBER OF SAMPLES CLASSIFIED INTO 2560 155 1959 FORAGE 403 9161 61 DECIDUOU CONIFER WATER 1314 247 1843 252 11553 11622 9 18129 18213 20 PCT. 56.2 72.9 67.3 95.6 6.06 69.3 11760 339 2676 32252 88 2679 NO OF SAMPS DECIDADO CONIFER SOYBEAN TOTAL GROUP FORAGE WATER CORN

OVERALL PERFORMANCE(31346/ 49794) = 63.0 AVERAGE PERFORMANCE BY CLASS(452.2/ 6) = 75.4

1730 319 2026 4250

487 2103 476 5278

9238 60

1572

27910

2676

SOYBE AN TOTAL

302

78.6 78.5 75.7

11760

FOR AGE CORN

98.5

339

89.8

CONIFER

WATER

only infrared channels considered. Classification results: Table 7.

1 972		CO = 0.0 CO = 0.0 CO = 0.0 CO = 0.0 CO = 32.70		·		
SEPT 13+1972		CALIBRAȚINN CODE = 1 CALIBRATION CODE = 1 CALIBRATION CODE = 1 CALIBRATION CODE = 1 CALIBRATION CODE = 1		CLASS FORAGE CORN SOYBFAN		59YBE AN 175 0
CLASSIFIED-		CALIBRA CALIBRA CALIBRA CALIBRA		4 4 6 CC 6 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8 8	# H	IFIED INTO E CORN 2211
913219703	CHANNELS USED	0.72 TO 0.92 MICROMETERS 1.00 TO 1.40 MICROMETERS 1.50 TO 1.80 MICROMETERS 2.00 TO 2.60 MICROMETERS 9.30 TO 11.70 MICROMETERS	CLASSES		TEST CLASS PERFORMANCE	NUMBER OF SAMPLES CLASSIFIED INTO DECIDUOU CONIFER WATER FORAGE CORN 27386 1491 0 989 2211
SEXIAL NUMBER		CHANNEL 8 SPECTRAL BAND CHANNEL 9 SPECTRAL BAND CHANNEL 10 SPECTRAL BAND CHANNEL 11 SPECTRAL BAND CHANNEL 12 SPECTRAL BAND		CLASS 1 DECIDUOU 2 CONIFER 3 WATER		NO OF PCT. SAMPS CORCT. 32252 84.9 6
		CHANNEL CHANNEL CHANNEL CHANNEL				GROUP

OVERALL PERFORMANCE(41166/ 49794) = 82.7 AVERAGE PERFORMANCE BY CLASS(506.0/ 6) = 84.3

Classification results: visible, middle infrared, thermal infrared channels considered. Table 8.

						CHANNELS USEU	JSEU			
CHANNEL	4	SPECTRAL BAND	BAND	0.52 TO		0.57 MICROMETERS	TERS	CALIBRATION CODE *	N CODE * 1	0.0 = 00
CHANNEL	9	SPECTRAL BAND	BAND	0.58 10	10	0.65 MICHOMETERS	TERS	CALIBRATION CODE	N CODE = 1	. 0*0 = 00
CHANNEL 10	01	SPECTRAL BAYD	BAND	1.50 TO	10	1.80 MICROMETERS	TERS	CALIBRATION CODE	V C00€ # 1	0.0 = 0.0
CHANNEL 11	11	SPECTRAL BAND	BAND		10	2.00 TO 2.60 MICROMETERS	TERS	CALIBRATION CODE	N C00E ≈ 1	0.0 = 03
CHANNEL 12	12	SPECTRAL BAND	BAND	9.30	10	9.30 TO 11.70 MICROMETERS	FERS	CAL LBRATION CODE *	N CDDE # 1	co = 32.70
						CLASSES	1			
	_	CLASS						CLASS	s	
	ā	DECIDADO						4 FORAGE	· Lu	
2	ပ	CONIFER						5 CORN		
æ	3	WATER	٠					6 SOYBEAN	AN	
				į	TES	TEST CLASS PERFORMANCE	ORMANCE			
ON.	90			N N	UER	NUMBER OF SAMPLES CLASSIFIED INTO	LAŚSIFI	LED INTO		
GROUP SA	SAMPS	CORCI	OECIDU	NO CON	I FER	DECIDUDU CONIFER WATER F	FORAGE CORN		SUYBEAN	

SUYBEAN 614

FORAGE 303

296

0

30281

93.9 95.5 6.16 83.4

32255 88 339 11.760 2679 2676

DECIDADO CGNI FER 1433 52 2597

485 2537

6086 80 57 1 02 60

18 3336

333

1041

30323

SOYBEAN

FORAGE WATER

CORN

AVERAGE PERFORMANCE BY CLASS(562.4/ 6) = 93.7 OVERALL PERFORMANCE! 45640/ 497941 = 91.7

Classification results: visible, near infrared, thermal infrared channels considered. Table 9.

						1						
CHANNEL	4	SPECTRAL BAND	BAND		10	0.57	0.52 TO 0.57 MICROMETERS	CAL	CALIBRATION CODE =	CODE =		0.0 = 00
CHANNEL	7	SPECTRAL BAND	BAND		10	0.70	0.61 TO 0.70 MICROMETERS	CAL	CALIBRATION CODE =	= 3GOO	e	0.0 = 0.0
CHANNEL	ಐ	SPECTRAL BAND	BAND	0.72	10	0.92	0.72 TO 0.92 MICROMETERS	CAL	CALIBRATION CODE =	= 3000		0.0 # 03
CHANNEL	ው	SPECTRAL BAND	BAND	1.00	10	1.40	1.00 TO 1.40 MICROMETERS	CAL	CALIBRATION CODE =	CODE =		0.0 = 0.0
CHANNEL 12		SPECTRAL	BAND	9.30	10	11.70	SPECTRAL BAND 9.30 TO 11.70 MICROMETERS	CAL	CALIBRATION CODE =	CODE =		C0 = 32.70
						;	CLASSES					
	3	CLASS							CLASS			
-	DEC	DECIDADO						4	FORAGE			
2	CON	CONTFER						ď	CDRN			
8	WATER	ER						9	SOYBEAN			

SUYBEAN

NUMBER OF SAMPLES CLASSIFIED INTO

FURAGE

WATER

DECIDUOU COMIFER

1201

29836

92.5

32252

DECIDADO

NO OF SAMPS

GROUP

604

2238 3828

1001

335

1306

29908

95.8

2412

TOTAL

SOYBEAN

2122

CORN

WATER FORAGE

9922

56

98.2 87.8 86.8

339

88

CONIFER

OVERALL PERFORMANCE: 44252/ 48515) = 91.2 AVERAGE PERFORMANCE BY CLASS: 550.2/ 6) = 91.7

Classification results: visible and thermal infrared channels considered. Table 10.

275 506 214 11601 OVERALL PERFORMANCE(34258/ 49794) = 68.8 19271 81.1 91.9 8.68 82.1 339 11760 2679 2676 SOYBEAN TOTAL FORAGE WATER CORN

AVERAGE PERFORMANCE BY CLASSI 487.9/ 6) = 81.3

SOYBEAN 1132

CORN 96 %

FORAGE 290

11485

19232

59.6

32252

DECIDOOU GROUP

CONTFER

77.3

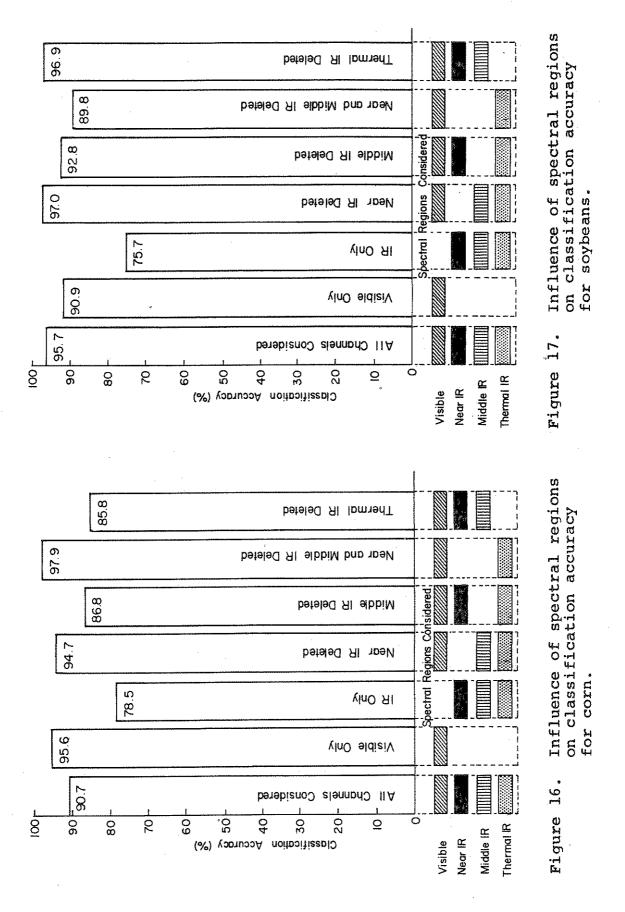
1386 33 2404

487 2623 151

ς. 4 9696 7 76

0





sequences, one or more spectral regions were deleted from consideration in the channel selection process, but in each case a total of five wavelength bands was actually used in the classification. It is of particular significance to note that the five wavelength bands actually utilized in the control classification (Table 5) included one in the green portion of the visible, one in the red portion of the visible, and one each in the near infrared, the middle infrared, and the thermal infrared regions.

Figure 10 illustrates the overall test results for the various analysis sequences. The first bar in the figure represents the test results provided by the control combination of channels which was selected upon consideration of all available channels. The remaining bars represent test results obtained from the five-channel combinations selected in the various other channel selection sequences. Because of its predominance in the segment, and hence in the test deck, the deciduous forest class has a greater effect than any other on the overall test results. For this reason, Figure 10 bears a close resemblance to Figure 12.

Figure 11 illustrates the high separability of forest cover (deciduous and coniferous forest combined) from other cover types, when various combinations of spectral regions were considered. In all but two cases the accuracy equaled or exceeded 95 percent. When only visible channels were considered (Table 6) a considerable amount of confusion

between forest and water resulted. Figure 3 illustrates that while the mean reflectance of the two forest categories is somewhat lower than that of water in the visible channels, there is still much overlap, which explains the confusion between these categories. Also note from Figure 3 that forest tends to have a significantly lower response than all three of the agricultural classes in the visible channels, so with only the visible channels considered, forest still separates from other cover types with an accuracy in excess of 90 percent.

The five infrared channels alone (visible excluded from consideration) were able to separate forest from other cover types with an accuracy of slightly less than 90 percent (Figure 11). In this case, forest was misclassified as corn and forage (Table 7). This would indicate that forest bears some resemblance to corn and forage in the infrared channels, resulting in confusion when the visible is not included to aid distinction. In all cases, however, there occurred at least some confusion between forest and the agricultural cover types.

A few of these misclassifications were valid. That is, grassy clearings in some of the forested test areas were often classified as forage, which indeed they were. For the most part, however, these misclassifications could probably be attributed to the fact that the highly illuminated

sides of tree crowns had spectral responses very similar to those of agricultural cover types.

with combined forest broken down into its two component categories, the classification results were more variable (Figures 12 and 13). A major source of error in all cases was that of deciduous being misclassified as conifer. In several cases, confusion between deciduous and the various agricultural cover types was also significant.

Tables 5-11 and Figure 12 list and illustrate the results for the deciduous forest class. When all channels were considered (Table 5), the largest single source of error was that of deciduous being misclassified as conifer in addition to some confusion with the three agricultual cover types. While the visible channels alone separated combined forest from other cover types with an accuracy of 92 percent (Figure 11), they did a very poor job of differentiating between deciduous and coniferous forest (Table 6, Figure 12). This confusion would be expected by anyone who has ever attempted to differentiate between deciduous and coniferous forest on either panchromatic or normal color photography. In general, conifers have a somewhat lower reflectance than deciduous trees in the visible wavelengths. However, the conifer stands present in Segment 218 were eastern white pine, which has a higher reflectance than most conifers. In fact, the coniferous forest training class actually exhibited a slightly higher mean reflectance than deciduous in the visible channels (Figure 3). These data support the statement that the difference between the deciduous and coniferous forest present in this segment was minimal in the visible portion of the spectrum.

Also, based on the visible wavelengths, a significant number of deciduous forest data points in the test areas were misclassified as water (Table 6). Figure 3 illustrates the spectral similarity between deciduous forest and water, in the visible wavebands, thus explaining the reason for this confusion.

The five infrared channels alone provided much improved separation between deciduous and coniferous forest (Table 7, Figures 12 and 13). Figure 3 illustrates the lower mean reflectance of conifer in the near and middle infrared, particularly in Channels 9 and 10. There was much confusion, however, between deciduous forest and two of the agricultural cover types, corn and forage.

Accuracy did not decrease, when the near infrared was deleted from consideration, (Table 8, Figure 12), nor did it suffer when middle infrared was deleted from consideration (Table 9). However, when both near and middle infrared were deleted so that only the visible and the thermal infrared were considered, recognition accuracies for deciduous forest dropped considerably (Table 10, Figure 12). Combined forest was still classified quite well when both

the near and middle infrared were deleted from consideration (Figure 11), but there was considerable confusion between deciduous and coniferous forest, and some confusion between deciduous and soybeans. Apparently the near infrared and the middle infrared regions serve the same function. Thus, while it is not necessary for both regions to be present, one of the two appears necessary for reliable forest cover mapping.

The results of the classification from which the thermal infrared was deleted (Table 11, Figure 12) show good separation between deciduous and conifer, as well as good separation between combined forest (Figure 11) and other cover types. The only problem appears to be some confusion between deciduous and forage (Table 11). This confusion might perhaps be explained by the differences in relative depth of the two canopies; that is, the deciduous forest presents a very deep canopy, perhaps 30-50 feet, while forage has a depth of only a few inches. These differences in relative depth would undoubtedly result in different thermal characteristics for the two cover types. If, in some instances, the only significant differences between two cover types were thermal-related, the presence of the thermal channel would be critical.

The principal source of error in the coniferous forest category (Figure 13) was that of conifers being misclassified as deciduous. The only case where conifer was

misclassified to any significant degree as something other than deciduous forest was where only the visible channels were used (Table 6). Here, there was some confusion between coniferous forest and water. The spectral similarities of coniferous forest and water in the visible channels are illustrated by Figure 3. For the most part, however, coniferous forest was highly separable (Figure 13).

In all but two cases, water easily separated from other cover types with a very high degree of accuracy (Figure 14). One exception was the case in which only visible channels were considered (Table 6). Here a considerable number of test points were misclassified as deciduous forest and forage. Researchers at LARS have previously noted and documented the similarities in the visible wavelengths between water, particularly turbid water, and many vegetative cover types (Figure 3). Thus, without the infrared channels present, confusion may be expected to re-The second instance of poor classification for the water category occurred where both the near and the middle infrared were deleted, indicating that, of the three infrared regions, these two are the most important for classifying water. This is borne out by the excellent results obtained when the thermal infrared channel was deleted from consideration (Table 11, Figure 14). This deletion caused no reduction in classification accuracy for water. It is interesting to note that in the channel number study

discussed earlier, the best single channel selected was Channel 10, in the middle infrared. This channel alone classified water with an accuracy in excess of 96 percent (Table 2, Appendix B). This is explained by the fact that in this particular wavelength band as in the others constituting the near and middle infrared regions, water has a substantially lower response than most other natural cover types (Figure 3).

Forage was used as a "catch-all" agricultural category, and consisted of pasture, hay, and stubble. As might be expected, it had an extremely wide spectral variance (Figure 3) and for the most part, gave a low classification accuracy relative to the other categories (Figure 15). In all cases the primary source of confusion occurred between forage and row crops. The only exception was when only infrared channels were considered (Table 7). In that case, a few forage test points were misclassified as deciduous forest. For the most part, however, confusion between the forest categories and forage was relatively insignificant. It is of importance to note that forage was the only category whose classification accuracy was substantially reduced by the deletion of the thermal channel (Table 11).

This confusion, allowed by the absence of the thermal infrared, concerned corn and soybeans. The row crop canopy, being deeper and more vigorous, was more influenced by the cooling effects of transpiration than the less vigorous

and constantly trampled pasture fields, periodically mowed hay fields, and harvested stubble fields constituting the forage class (Figure 3). The absence of the thermal infrared channel, then, would be expected to result in a certain amount of confusion.

As with forage, there was little confusion between the row crop categories (corn and soybeans) and the forest categories. Misclassification, for the most part, consisted of confusion between the three agricultural cover types, i.e. forage, corn and soybeans (Tables 5-11, Figures 15-17). This confusion did not affect, and in fact, was of little interest to the objectives of this study.

To summarize, it would appear that, for forest cover mapping, the various spectral regions do differ significantly in relative value. The visible channels alone seem to do a good job of separating combined forest from other cover types, but are inadequate as far as differentiating between deciduous and coniferous forest. The infrared channels alone, on the other hand, seem to perform well in differentiating between deciduous and coniferous forest, but are not as satisfactory as the visible for separating forest in general, and deciduous in particular, from other, nonforest, cover types. The logical conclusion, then, would be that both the visible and the infrared channels are necessary for accurate hasic forest cover mapping. When either the near or the middle infrared are deleted

individually, accuracies remain high, but when both are deleted at the same time, accuracy drops considerably. On the other hand, when the thermal infrared is deleted, the drop in accuracy is slight. This would indicate that of the infrared wavelengths, the reflective infrared (near and middle infrared) is the most important, and that only one of the two reflective infrared wavelength regions is really necessary to obtain good results. This conclusion seems to be supported by the results thus far obtained in the analysis of ERTS multispectral scanner data, which is recorded in two visible and two near infrared channels. The information contained in these four channels seems to be sufficient for accurate basic forest cover mapping (Landgrebe et al. 1972).

This is not to say, however, that the thermal region is unimportant. It is interesting, and of some significance, to note that the separability processor always selected at least one channel from each of the spectral regions which it was allowed to consider. For instance, when it was allowed to consider all twelve channels, i.e. all four spectral regions, it selected two visible, one near infrared, one middle infrared, and the thermal infrared channel. Likewise, in all other cases, it selected at least one channel from each of the available spectral regions. This would indicate that in general, all four regions are important, even though their relative values may vary.

A second set of twelve-channel MSS data, acquired the same day over similar cover types near the Ohio River, was analyzed in the same manner as Segment 218. While the classification accuracies deviated from those described above, the trends were similar, and tended to substantiate the above stated conclusions.

MSS-Digitized CIR Comparison

The results of the comparisons between MSS data and digitized color infrared photography are listed and illustrated in Tables 12-15 and Figures 18, 19 and 27. The three MSS data channels used in this comparison were those which most closely approximated the wavelength bands of the color infrared photos (Figure 7). In general, the digitized photography compared poorly, especially where the perpoint classifications were concerned (Tables 12 and 13 and Figure 18). The greatest discrepancy in classification accuracy between the two sets of data occurred in the forest categories, particularly deciduous forest.

In the MSS data, the primary source of confusion for deciduous forest was with coniferous forest, and vise versa (Table 12). In fact, a mathematical combination of the two forest classes revealed a classification accuracy for combined forest of 93.6 percent with only three channels. The remaining classes, with the exception of forage which was badly confused with row crops, were

Perpoint classification results: multispectral scanner data using three channels corresponding to color infrared film bands. Table 12.

17.2		0.0 = 00 0.0 = 00							
IED- DEC 15,1972		CALIBRATION CODE = 1 C CALIBRATION CODE = 1 C CALIBRATION CODE = 1 C		CLASS	FURAGE		CUKN	SOY	
CLASSIFIED-		*			4	. 1	ın.	.	Li Ci Zi
	CHANNELS USED	SPECTRAL BAND 0.52 TO 0.57 MICROMETERS SPECTRAL BAND 0.61 TO 0.70 MICROMETERS SPECTRAL BAND 0.72 TO 0.92 MICROMETERS	CLASSES						TEST CLASS PERFORMANCE
- 121		0.5						*	
		BAND BAND BAND							
SERIAL MUMBER 1215206803		SPECTRAL BAND SPECTRAL BAND SPECTRAL BAND		00410	CLASS	DECIO	CUNIFER	WATER	
SERI		z ~ z				_	_	-	
		CHANNEL CHANNEL CHANNEL				1	2	3	

					NUMBER OF	NUMBER OF SAMPLES CLASSIFIED INTO	CLASSIFI	ED INTO	
	distract	NO OF POWER	CORCI	DECID	CONIFER	WATER	FORAGE	CORN	SOY
· 3	2004		63.9		3133	4	433	191	1460
5 3	CECTE	3 80 3 80 3 80 3 80 3 80 3 80 3 80 3 80	8 68	•	19	0	0	0	0
ב כ		0 6	46.2		6	326	-	2	0
E L	1 C C C C C C C C C C C C C C C C C C C	11766		7.	10	1.2	7533	5052	1795
L (.	LUNAGE	2619		9	2	0	1.1	2613	24
S	SOY	2676		43	0	0	44	11.4	2475
	TOTAL	46164		27119	3233	342	8028	5245	

AVERAGE PERFURMANCE BY CLASS(523.9/ 6) = 87.3 OVERALL PERFORMANCE! 40087/ 49794) = 80.5

Perpoint classification results: digitized color infrared photography using all three channels. Table 13.

NOV 30,1972		CALIBRATION CODE = 1 CO = 0.0 CALIBRATION CODE = 1 CO = 0.0 CALIBRATION CODE = 1 CO = 0.0		CLASS	FORAGE	CORN	>-			Suy	2956	1	0	883	16	1661	5387
CLASS1F1ED-		CALIBRA CALIBRA CALIBRA		J	4 FC	00 S	40S 9	ا ا الا	NUMBER OF SAMPLES CLASSIFIED INTO		10389	~	0	1957	1525	106	13984
	CHANNELS USED	MICROMETERS MICROMETERS MICROMETERS	CLASSES					TEST CLASS PEREDRMANCE	ES CLASSI	FURAGE	156	0	4	8172	43	31	9201
	CHANNEL	0.61 MICROMETERS 0.71 MICROMETERS 0.89 MICROMETERS	CLASSES					ST CLASS	OF SAMPL	R WATER	100	ľV	450	27	0	0	1182
SERIAL NUMBER 1130206803		0.47 TU 0.59 TO 0.68 TO						TES	NUMBER	COMIFER	7367	81	~	109	133		8136
		SPECTRAL BAND SPECTRAL BAND SPECTRAL BAND								DECID	12607	33	0	345	301	83	13369
L NUMBE		SPECTRAL SPECTRAL SPECTRAL		55 0 13	DECID	CONTEER	WATER			CORCT	36.1	63.8	91.6	68.2	75.6	87.1	
SEALA		et 1 EL 2 EL 3			, ,,					VO OF SAMPS	34970	127	451	11985	2018	1758	51319
		CHANNEL CHANNEL CHANNEL								GROUP	DEC 10	CONIFER	WATER	FORAGE	CORN	SOY	TOT AL
												~	m	4	S	9	

OVERALL PERFORMANCEI 24366/ 51319) = 47.5 AVERAGE PERFORMANCE BY CLASSI 428.37 6) = 71.4

scanner data using three channels corresponding to color infrared film bands. multispectral Perfield classification results: Table 14.

		SOY	0	0	0	1	0	23	30
	AS	CORN	0	O	0	2.1	10	1	38
	NUMBER OF FIELDS CLASSIFIED AS	FORAGE	O	0	0	44	0	0	46
JMMARY	FIELDS	WATER	0	0	15	0	0	0	15
PERFORMANCE SUMMARY	NUMBER OF	CONIFER	0	4	0	0	0	0	4
PERF		01030	94	0	0	0	0	0	46
		NO JF PCT SAM SAMS CORRECT	100.0	100.0	100.0	63.4	100.0	97.9	91.2
			32252	88	339	11763	5673	26 75	49794 3
		PCT FLD CORRECT	100.0	100.0	100.0	51.5	100.0	95.8	80.4
		NO OF	46	4	1.5	80	10	24	119
		CLASS	0ECI)	CONIFER	#ATE?	FORASE	CORN	SOY	TOTALS
			-	2		4	2	9	

Perfield classification results: digitized color infrared photography using all three channels. Table 15.

					PER	PERFORMANCE SUMMARY	UMMARY				
						NUMBER OF	FIELDS	UMBER OF FIELDS CLASSIFIED AS	AS		
CLASS	NO OF	PCT FLO CORRECT	SAMS	PCT SAM CORRECT	DECID	CONTFER	MATER	FORAGE	CORN	₹ns	
01030	4.5	84.4	84.4 134849	84.4	3.8	-	0	0	9	0	
CONIFER	4	75.6	418	82.1	-	ĸ	0	0	0	0	
WATER	15	100.0	1489	100.0	0	0	15	0	0	0	
FORAGE	73	78.1	44173	68.1		ښن	0	57	13	••••	
CORN	ĸ	80.0	1741	91.4		0	0	0	4	0	
\$0X	16	87.5	6322	94.0	0	0	0			14	
TOTALS	158	65.9	82.9 194992	81.4	41	ïV.	15	58	24	15	



poor results were probably due, at least in part, to inadequate training for the digitized photographic data. What was sufficient for the MSS data was apparently inadequate for the digitized color infrared photography. Since the plan of analysis did not call for alteration of the training deck for the benefit of the digitized photography, however, the inadequacy of the training deck cannot be substantiated.

An examination of Figure 4, reveals the apparent lack of spectral contrast between the training classes in Channels 1 and 2 of the digitized photography (with the exception of forage). Only in Channel 3 do there appear to be any significant spectral differences, and even there the forest classes show much similarity. The MSS data, on the other hand, (Figure 3) exhibits much more contrast in the three corresponding channels (four:0.52-0.57 μm , seven:0.61-0.70 μm , and eight: 0.72-0.92 μm). In all three MSS channels, the two forest classes appear to have a significantly lower response than the three agricultural classes (Figures 3, 20, and 22) with water plainly separable in Channel 8 (Figure 3). In general, then, according to the relative differences shown on the cospectral plots of Figures 3 and 4, the digitized photography has a narrower dynamic range with less contrast between the training classes. that there is greater contrast between general forest and other cover classes in the MSS data than in the digitized photography is evident in Figures 24 and 25.

Another problem may be the limited number of channels available. The spectral region evaluation study, based on various five-channel combinations, concluded that the visible and near-infrared portions of the spectrum should be adequate for accurate forest cover mapping. However, when these two regions were represented by only three channels, (MSS Channels 4, 7, and 8 for purposes of the comparison between the digitized photographic data and the MSS data), the results did not reflect those obtained with the use of five channels. Of further note is the channel number study in which the feature selection processor selected the "best" three-channel combination from the visible, middle infrared, and thermal infrared and still fell short of 90 percent overall classification accuracy (Table 2, Figure 5). Since the number of channels used in a classification determines the number of dimensions, in space, in which decision boundaries are established by the classification algorithm, one might conclude that three dimensions or channels are simply not enough, especially when those channels which are available are limited to the visible and the near infrared portions of the spectrum.

The discrepancies in classification accuracies between the two data sets are less in the perfield classification results (Tables 14 and 15, Figure 19) than in the perpoint results. In addition, for the most part, the perfield classification results are substantially higher, with the

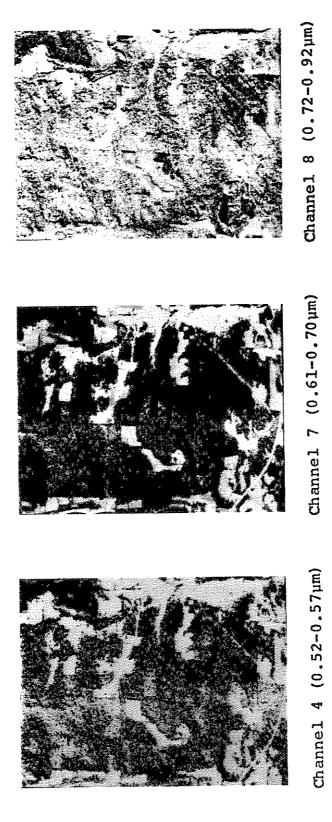
exception of forage which actually decreased slightly where the MSS data was concerned. Several classes (including both forest classes) were classified with an accuracy of 100 percent, in the MSS imagery.

Past work at LARS has indicated that accuracies almost always tend to be higher with the perfield classifier. By looking at the test field as a whole, dissimilar individual data points are averaged in with all the other points in the test field. While they have an influence on both the mean and standard deviation of the test field, such dissimilar points are not classified individually based on their own spectral characteristics, but rather with the remainder of the test field as one decision. In effect, then, the perfield classifier considers spatial as well as spectral information. This is a basic and extremely important aspect of this classifier.

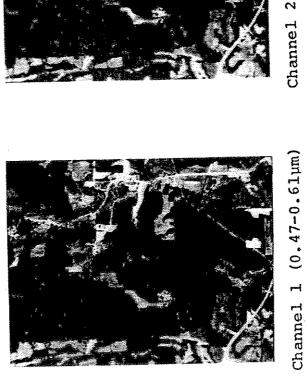
Despite the appearance of tendencies and trends, the validity of comparing these two types of data (digitized photography and MSS) is somewhat questionable. While the two types of data may be processed to the same format, amenable to the same analysis techniques, their acquisition is by entirely different means; the scanner being electronic in nature, while the photographic emulsion is chemical.

Both good and poor results have been reported concerning the automatic analysis of digitized multiemulsion photography. While the results of this study are

inconclusive, suffice it to say that automatic analysis of photographic data should be approached with extreme caution. Though photography is cheaper and easier to acquire than scanner data, and is easily interpreted manually, the narrower dynamic range, the illumination problems within this photographic data set, and the fact that the data was limited to only three channels, (and hence only three dimensions in the classifier) seem to pose serious limitations to its analysis by the ADP techniques utilized in this study. The qualitative nature of the photographic emulsion simply does not lend itself, to reliable quantitative analysis.



images of the northern portion of Seg. 218: 7, and 8. Digital display MSS Channels 4, Figure 20.



Channel 2 (0.59-0.71µm)



Channel 3 (0.68-0.89µm)

Digital display images of the northern portion of Seg. 218: digitized color infrared photo, Channels 1, 2, and 3. Figure 21.

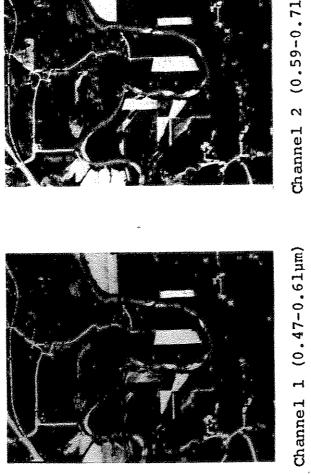


Channel 8 (0.72-0.92µm)

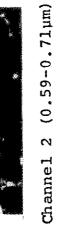
Digital display images of the southern portion of Seg. 218: MSS Channels 4, 7, and 8. Figure 22.

Channel 7 (0.61-0.70µm)

Channel 4 (0.52-0.57µm)





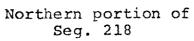




Channel 3 (0.68-0.89µm)

Digital display images of the southern portion of Seg. 218: digitized color infrared photo, Channels 1, 2, and 3. Figure 23.





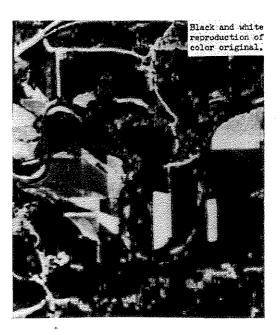


Southern portion of Seg. 218

Figure 24. Color infrared reconstitution of Seg. 218 using MSS data, Channels 4, 7, and 8.



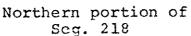
Northern portion of Seg. 218

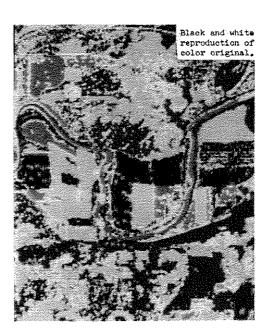


Southern portion of Seg. 218

Figure 25. Color infrared reconstitution of Seg. 218 using digitized color infrared photographic data, Channels 1, 2, and 3.





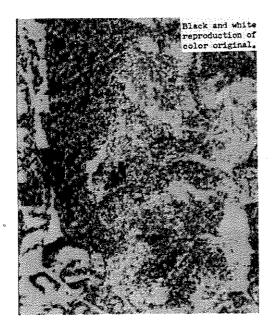


Southern portion of Seg. 218

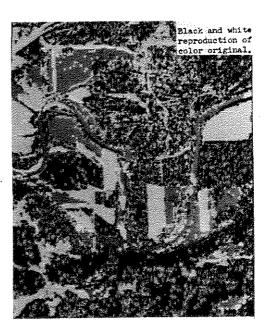
LEGEND

deciduous forest....green coniferous forest....black water.....blue forage.....yellow corn....red soybeans....magenta

Figure 26. Classification results for MSS data: best combination of five channels (4, 6, 9, 10, and 12).



Northern portion of Seg. 218



Southern portion of Seg. 218

LEGEND

deciduous forest....green coniferous forest...black water....blue forage....yellow corn....red soybeans....magenta

Figure 27. Classification results for digitized color infrared photographic data, using all three channels.

CHAPTER V

CONCLUSIONS AND RECOMMENDATIONS

Conclusions

Channel Number Study

For the purposes of this project, the use of five channels seemed to provide the best compromise between classification accuracy and computer time (Figure 5). This conclusion, however, was developed without a cost-benefit analysis. Different circumstances and additional input might well result in a different conclusion.

Forest Mapping Capability

The capability exists to reliably map forest cover using multispectral scanner data and automatic data processing techniques. The use of five of the available twelve scanner channels differentiated forest from other cover types with an accuracy in excess of 95 percent (Table 2, Figure 6). In addition, the classifier algorithm was able to differentiate between deciduous and coniferous forest

with accuracies well in excess of 90 percent (Tables 2 and 3, Figure 6). The use of all of the available twelve channels elicited only a slight increase in overall accuracy (Tables 2 and 4, Figure 7).

Spectral Region Evaluation

Results from two sets of data indicate that all four spectral regions (visible, near infrared, middle infrared, and thermal infrared) are valuable in forest cover mapping. Accurate results appear attainable, however, with the visible and either the near or the middle infrared. The visible alone seems to do a good job of separating general forest from other cover classes, but a poor job of differentiating between deciduous and coniferous forest. The near and middle infrared, on the other hand, are quite adequate for separating the two forest classes from each other, but leave some confusion between deciduous forest and other classes of vegetation. Accurate forest cover mapping results appear attainable when the visible is combined with either the near or the middle infrared. This conclusion compares favorably with early results of forest cover mapping using ERTS-1 data. The thermal infrared appears to be desirable, but not necessary for reliable forest cover mapping. this study, as well as previous investigations have indicated, however, the thermal infrared is very useful in differentiating many non-forest cover types.

MSS-Digitized CIR Comparison

The results obtained in this study indicate the inadequacy of digitized color infrared photography in the area
of forest cover mapping with ADP techniques. While the
photography was easily interpreted manually, it had several
characteristics which severely limited its analysis, in a
digital format, by ADP techniques. The narrower dynamic
range tended to limit contrast between training classes,
and the illumination problems in the original exposure
caused considerable confusion. While both the visible and
the near infrared portions of the spectrum were present
in the digitized photographic data, the fact that these
spectral regions were divided into only three rather broad
channels (Figure 7), may have been partly responsible for
the poor results.

Recommendations

It is recognized that the results obtained in this research cover a somewhat limited set of circumstances. The data was all obtained the same day, over the same geographic area, under similar atmospheric conditions, and without variation in the configuration of the instrumentation used. Given a different set of circumstances and objectives, the conclusions might differ from those obtained in this study. In view of these limitations, the following areas are recommended for expanded study:

- 1. Determine basic forest cover mapping capability with ERTS data for various geographic areas and seasons.
- 2. Determine the utility of the various spectral regions for other objectives (agriculture, geology, land use, hydrology, etc.) during the various seasons.
- 3. Evaluate, in detail, the various wavelength bands within the four spectral regions.
- 4. Evaluate the effects of the <u>digitization rate</u> of photographic data on its performance for forest cover mapping with automatic data processing techniques.
- 5. Evaluate <u>temporal changes</u> in the spectral characteristics of forest species from data acquired at <u>various</u> altitudes.

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APPENDICES

APPENDIX A

Table 1A

Training and test fields used for analysis of multispectral scanner data: Run 71052501.

Table 1A

SAVED TRAINING FIELDS

	RUN NUMBER	FIELD DESIG.	FIRST	LAST	LINE INT.	FIRST COLUMN	LAST COLUMN	COLUMN INT.	FIELD TYPE	OTHER INFORMATION	CLASSIFY
				****				1	DECID	FOREST	DECID
i	71052501	TRN519	519	525		26	32 192	1	DECID	FOREST	DECID
2	71052501	TRN173	173	188	1	186 67	70	1	CONIFER	FOREST	CONTFER
3	71052501	TRN46	46	49	1	76	78	1	CONIFER	FOREST	CONIFER
4	71052501	TRN48	48	48	1	66	67	1	CONFER	FOREST	CONIFER
5	71052501	TRN52	52	53 55	1	73	77	1	CONTEER	FOREST	CONTFER
6	71052501	TRN55	55	72	ı	52	52	1	CONIFER	FOREST	CONIFER
7	71052501	TRN68	333	339	1	83	88	Ĺ	CONIFER	FOREST	CONIFER
8	71052501 71052501	TRN333 TRN396	396	399	1	109	126	i	CONTFER	FOREST	CENTFER
9	71052501	TRN1217	1217	1219	1	75	80	1	RIVER	WATER	WATER
- 11	71052501	TRN1174	1174	1174	1	197	202	ı	RIVER	WATER	WATER
12	71052501	TRN1216	1216	1217	į.	68	73	1	RIVER	WATER	WATER
13	71052501	TRN1239	1239	1245	i	7.7	80	1	RIVER	WATER	WATER
14	71052501	TRN1273	1273	1282	1	74	76	1	RIVER	WATER	WATER
15	71052501	TRN1290	1290	1294	1	82	85	1	RIVER	WATER	WATER
16	71052501	TRN1291	1291	1293	1	140	143	1	RIVER	WATER	WATER
17	71052501	TRN877	877	879	1	41	45	1	POND	WATER	WATER
18	71052501	TRN1175	1175	1175	1	11	20	1	RIVER	WATER	WATER
19	71052501	TRN1184	1184	1185	1	30	32	Ł	RIVER	WATER	WATER
20	71052501	TRN146	146	148	1	108	112	1	POND	WATER	WATER
21	71052501	TRN151	151	155	1	113	119	1	POND	WATER	WATER
22	71052501	TRN155	155	159	i	120	129	1	POND	WATER	WATER
23	71052501	TRN155	155	156	1	23	24	1	POND	WATER	WATER
24	71052501	TRN227	227	228	ı	52	53	1	POND	WATER	WATER
25	71052501	TRN337	337	338	i.	108	111	ì	POND	WATER	WATER
26	71052501	TRN8 3.1	831	834	1	11	14	1	POND	WATER	WATER
27	71052501	TRN843	843	846	1	4	8	1		WATER	WATER
28	71052501	TRN847	847	849	L	2	5	i		WATER	WATER
29	71052501	TRN506	506	510	i		86	Ł	PASTURE	FORAGE	FORAGE FORAGE
30	71052501	TRN650	650	654	ı		56	ı.		FORAGE	- FORAGE
31	71052501	TRN335	335	339	1		204	1		FORAGE	FORAGE
32	71052501	TRN564	564	574	L		217	1		FORAGE	FORAGE
33	71052501	TRN405	405	419	l		215	l.		FORAGE	FORAGE
34	71052501	TRN32	32	35	1			1		FORAGE	FORAGE
35	71052501	TRN56	56	67	I			1		FORAGE	FORAGE
36	71052501	TRN196	196	204	1			ì		FORAGE	FORAGE
37	71052501	TRN1143	1143	1152	1			1		FORAGE	FORAGE
38	71052501	TRN1449	1449	1452	1			1		FORAGE	FORAGE
39	71052501	TRN853	853	859	1					FORAGE	FORAGE
40	71052501	TRN817	817	825 1284	1					FORAGE	FORAGE
41	71052501	TRN1275	1275 105	111						FORAGE	FORAGE
42	71052501	TRN105		127					STUBBLE	FORAGE	FORAGE
4.3	71052501	TRN115 TRN1202	115 1202	1209		1 184				FURAGE	FORAGE
44	71052501	TRN1189	1189	1193		1 184			L STUBBLE	FORAGE	FORAGE
45	71052501	TRN678	678	681		1 173			STUBBLE	FORAGE	FORAGE
46 47	71052501 71052501	TRN1250	1250	1257		1 93			CORN	¢O.M	CORN
48	71052501	TRN1275	1275	1282		1 93)]	L CORN	ROW	CORN
49	71052501	TRN1403	1403	1412		194			1 CORN	ROW	CORN
50		TRN1492	1492	1506		1 3			1 CORN	ROW	CORN
51		TRN1481	1481	1485					1 CORN	ROW	CORN
52		TRN1487	1487	1512		1 4		!•	1 CORN	RD₩ [™]	CORN ,
53		TRN661	661	670		1 17	4 183	L	1 CORN	ROW	CORN
54		TRN681	681	685		1 13	7 143	3	1 CORN	ROM	CORN
5 5		TRN683	683	685		1 15	3 16	7	1 CORN .	ROW	CORN
56		TRN698	698	703	3	1 14	1 14	3	1 CORN	ROW	CORN

Table 1A, cont.

	м						125		SOY	ROW	SOY
57	71052501	TRN1253	1253	1274	1	129	135	•	301	-	CON
		TRN1191	1191	1193	1	43	46	1	SDY	ROW	SOY
58	71052501	IKMITAT				***	90	1	SOY	RÖW	SOY
59	71052501	TRN1473	1473	1479	ı	78	90	•			env
· .		TRN1027	1027	1031	1	5	25	Į.	SDY	ROW	YOZ
60	71052501	IKNIOZI	TOE .	=	Ī		128	3	YOZ	BOM	SOY
61	71052501	TRN1045	1045	1048	1	124	120	*	30.		50V
	71052501	TRN498	498	500	ı	99	117	ì	SOY	8 O W	SQY

SAVED TEST FIELDS

	RUN NUMBER	FIELD DESIG.	FIRST	LAST LINE	LINE INT.	FIRST COLUMN	LAST COLUMN	COLUMN INT.	FIELD TYPE	OTHER INFORMATIO:	DISPLAY CLASS
				25	ì	61	157	ı	DECID	FOREST	DECID
ì	71052501	TESTI	1 43	bi	1	122	156	i	DEC 10	FOREST	DECID
2	71052501	TEST43	48	88	1	161	179	ì	DECID	FUREST	DECIU
3	71052501	TEST48	72	83	i i	113	137	1	0 E.C. 1 D	FOREST	DECID
4	71052501	TEST72	77	107	1	1	22	1	DECID	FUREST	DECTO
5	71052501	TEST77	88	110	ı	107	138	ı	DECID	FOREST	DECID
6	71052501	T£ST88 T£ST91	91	122	ı	160	178	1	DECID	FOREST	DECID
7	71052501	1E3191	98	134	1	73	93	1	DECID	FOREST	DECID
8	71052501 71052501	TEST123	123	144	1	115	128	l	DECID	FOREST	DECID
9		TEST149	149	158	1	59	103	1	DECID	FOREST	DEC10
10	71052501	TEST116	116	161	1	6	19	1	DECID	FOREST	DECID
11	71052501	TEST150	150	190	1	212	222	1	DECID	FOREST	DECID
12	71052501	TEST191	191	209	1	123	160	į	DECID	FOREST	DECID
13	71052501	TEST220	220	261	1	200	222	1	DECID	FOREST	DECIO
14	71052501	TEST245	245	286	1	140	155	1	DECID	FUREST	DECID
15	71052501	TEST246	246	262	ì	177	200	1	DECIO	FOREST	DECID
16	71052501	TEST256	256	295	1	43	54	1	DECID	FOREST	DECID
17	71052501	TEST297	297	316	l		64	1	DECID	FOREST	0103d
18	71052501	TEST312	312	325	1		184	1	DECID	FOREST	DECID
19	71052501	TEST317	317	361	ł		40	ì	DECID	FOREST	DECID
20		TEST342	342	366	1		133	1	DECID	FOREST	DECID
21	71052501	TEST339	339	352	1	166	192	1.	01030	FOREST	DECID
22	71052501 71052501	TEST386	386	403	1	42	58	1	DECID	FOREST	0 6 6 1 0
23		TEST386	386	404		. 60	68	ì	DECID	FOREST	DECID
24	71052501	TEST371	371	390		119	188	i	DECID	FOREST	DECIU
25	71052501	TEST390	390	402		1 145	172	1	DECID	FOREST	DECID
26	71052501	TEST408	408	429		160	183	. 1	DECID	FOREST	DECID
27	71052501	TEST437	437	446		149	153	i	DECID	FOREST	01036
26	71052501	TEST431	431	455		141	148	, 1	DECID	FOREST	DECID
29	71052501	TEST464	464	491	_	1 199	210) 1	DEC10	FOREST	DECID
30 31	71052501	TEST508	508	526	>	1 90	9 126	, 1	DECID	FOREST	DECID
32	71052501	TEST466	466	475	,	1	Į 27	! 1	DECID	FOREST	DECID
33	71052501	TEST519	519	540)	1 3	3 40)	DECID	FOREST	DECID
34	71052501	TESTS75	575	578	š	1 17	7 183	L	01030	FUREST	01030
35	71052501	TEST575	575	602	2	1 16	1 176	5	DECID	FOREST	DECID
36		TEST631	631	641	7	1 19	0 22	2	1 DECID	FOREST	0EC10
31		TEST635	635	64	4	1 5	8 7	3	i DECID	FOREST	DECID
38		TEST657	657	67	7	1 10	7 17	6	1 DECID	FOREST	D£C10
39		TEST785	785	82	6	1 13	6 20	3	1 DECID	FOREST	necio
40		TEST814	814	85	4	1 3	1 5	1	I DECID	FOREST	06010
41		TEST858	858	87	0 -	1 18	0 22	2	1 DECID	FUREST	05010
42		TEST935	935	97	4	L 4	6 11	1	1 DECID	FOREST	DECID
4.3		TEST100	7 1007	106	ხ	1 18	3 21	1	1 DECID	FOREST	DECID
40		TEST107	9 1079	109	8	1 9	9 13	0	1 DECID	FOREST	DECID
45				121	8	1 9	11	5	1 DECID	FOREST	06010
46				136	9	1 18	9 22	2	1 DECED	FOREST	DECID
4			344	34	8	1	74 7	7	1 CONTFER		CONTER
44			409	41	1	1 14	5 15	0	1 CUNIFER		CUNIFER CONIFER
4			413	4.2	U	1 14			1 CONIFER		CONTER
51			512	51	4	1 14	44 14	9	1 CONTEEP	FOREST	CLMIFER

Table 1A, cont.

51	71052501	TESTŽ94	294	295	ì	158	159	1	POND	WATER	WATER WATER
52	71052501	TEST834	834	837	1	4	10	1	POND	WATER	WATER
53	71052501	TEST1214	1214	1227	1	7	7	1	RIVER	WATER	
54	71052501	TEST1219	1219	1230	1	83	86	1	RIVER	WATER	WATER WATER
55	71052501	TEST1191	1191	1192	ı	164	167	1	RIVER	WATER	WATER
56	71052501	TEST1195	1195	1200	1	161	162	i	RIVER	WATER	WATER
57	71052501	TEST1224	1224	1238	1	161	164	1	RIVER	WATER	
58	71052501	TEST1213	1213	1214	1	58	63	1	RIVER	WATER	WATER
59	71052501	TEST1252	1252	1259	i	80	82	1	RIVER	WATER	WATER WATER
60	71052501	TEST1261	1261	1267	1	157	159	1	RIVER	WATER	
61	71052501	TEST1279	1279	1282	1	153	155	1	RIVER	WATER	WATER
62	71052501	TEST1285	1285	128/	1	149	150	1	RIVER	WATER	WATER
63	71052501	TEST1297	1297	1299	1	121	126	i	RIVER	WATER	WATER
64	71052501	TEST1206	1206	1215	1	163	166	1	RIVER	WATER	WATER
65	71052501	TEST1216	1216	1223	1	162	165	1	RIVER	WATER	WATER
66	71052501	TEST10	10	15	1	23	30	1	PASTURE	FORAGE	FORAGE
67	71052501	TEST135	135	140	1	163	174	ì	PASTURE	FORAGE	FORAGE
68	71052501	TEST141	141	144	ì	153	164	1	PASTURE	FORAGE	FORAGE
69	71052501	- FEST121	121	142	1	215	222	1	PASTURE	FORAGE	FORAGE
70	71052501	TEST164	164	169	ì	179	184	1	PASTURE	FORAGE	FORAGE
71	71052501	TEST182	182	187	L	115	135	1	PASTURE	FURAGE	FORAGE
72	71052501	TEST205	205	211	1	2	7	1	PASTURE	FORAGE	FORAGE
73	71052501	TEST216	216	` 219	1	128	134	1	PASTURE	FURAGE	FURAGE
74	71052501	TEST235	235	241	ì	157	164	1	PASTURE	FORAGE	FORAGE
75	71052501	TEST230	230	237	1	122	133	ì	PASTURE	FORAGE	FORAGE
76	71052501	TEST291	291	296	1	140	149	1	PASTURE	FORAGE	FORAGE
77	71052501	TEST288	288	297	1	124	132	ì	PASTURE	FORAGE	FORAGE
78	71052501	TEST300	300	308	ì	153	157	1	PASTURE	FORAGE	FORAGE
79	71052501	TEST272	272	280	1	211	222	1	PASTURE	FORAGE	FORAGE
80	71052501	TEST350	350	357	1	145	160	1	PASTURE	FORAGE	FORAGE
81	71052501	TEST330	330	337	ı	47	51	1	PASTURE	FORAGE	FORAGE
8.2	71052501	TEST382	382	399	ì	197	208	. 1	PASTURE	FORAGE	FORAGE
83	71052501	TEST420	420	431	1	208	215	. 1	PASTURE	FORAGE	FORAGE
84	71052501	TEST408	408	417	Ł	51	58	1	PASTURE	FORAGE	FORAGE
85	71052501	TEST426	426	429	ı	27	35	1	PASTURE	FORAGE	FORAGE
86	7,1052501	TEST458	458	467	Ł	113	119	1	PASTURE	FORAGE	FORAGE
87	71052501	TEST463	463	469	1	175	182	l	PASTURE	FORAGE	FORAGE
88	71052501	TEST471	471	483	ı	173	184	1	PASTURE	FORAGE	FORAGE
89	71052501	TEST486	486	496	ì	151	159	1	PASTURE	FORAGE	FORAGE
90	71052501	TEST475	475	495	1	56	67	1	PASTURE	FORAGE	FURAGE
91	71052501	TEST499	499	508	i	23	28	1	PASTURE	FORAGE	FORAGE
92	71052501	TEST499	499	509	1	42	52	1	PASTURE	FORAGE	FORAGE
93	71052501	TEST491	491	501	1	76	94	1	PASTURE	FORAGE	FORAGE
94"		TEST532	532	550	1	88	102	1	PASTURE	FORAGE	FORAGE
95	71052501	TEST543	543	551	ı	127	140	Ł	PASTURE	FORAGE	FORAGE
96	71052501	TEST564	564	570	ì	127	165	1	PASTURE	FORAGE	FORAGE
97	71052501	TEST582	582	591	1	206	222	1	PASTURE	FORAGE	FORAGE
98	71052501	TEST572	572	580	1	48	55	l	PASTURE	FORAGE	FORAGE
99	71052501	TEST559	559	565	ı	24	35	ı	PASTURE	FORAGE	FORAGE
100	71052501	TEST619	619	628	i	84	99	1	PASTURE	FORAGE	FORAGE
101	71052501	TEST634	634	647	1	137	147	1	PASTURE	FORAGE	FORAGE
	71052501	TEST649	649	663	1	133	169	1	PASTURE	FORAGE	FORAGE
102		TEST649	649	655	1	195	210	1	PASTURE	FORAGE	FORAGE
103		TEST693	693	704	1	115	125		PASTURE	FORAGE	FORAGE
104		TEST700	700	703	1	178	203		PASTURE	FORAGE	FORAGE
105			881	888	ì	106	132		PASTURE	FORAGE	FORAGE
106		TESTER	908	916	1	29	39		L PASTURE	FURAGE	FORAGE
107		TEST908	969	976	1	153	172		1 PASTURE		FORAGE
108		TEST969		968	1	169	181		1 PASTURE		FORAGE
109		1EST954	954 985	350	1	106	130		PASTURE		FORAGE
110		TEST985	1021	1039	1	32	41		1 PASTURE		FORAGE
111		TEST1021			ı	59	83		1 PASTURE		FORAGE
112	71052501	TEST1089	1089	1098		, ,	0.2				

Table 1A, cont.

113	71052501	TEST1075	1075	1084	1	146	163	ı	PASTURE	FORAGE	FORAGE
114	71052501	TEST1123	1123	1129	1	117	133	ì	PASTURE	FORAGE	FORAGE
115	71052501	TEST1131	1131	1140	1	123	147	1	PASTURE	FORAGE	FORAGE
116	71052501	TEST1162	1162	1175	1	166	181	1	PASTURE	FORAGE	FORAGE
117	71052501	TEST1196	1196	1206	1	134	146	1	PASTURE	FORAGE	FORAGE
118	71052501	TEST1179	1179	1186	ı	85	102	1	PASTURE	FORAGE	FORAGE
119	71052501	TEST1343	1343	1356	Ł	50	59	1	PASTURE	FORAGE	FORAGE
120	71052501	TEST1313	1313	1317	1	164	180	ì	PASTURE	FORAGE	FORAGE
121	71052501	TEST1360	1360	1384	. 1	166	180	Ł	PASTURE	FORAGE	FORAGE
122	71052501	TEST1390	1390	1400	1	184	222	1	PASTURE	FORAGE	FORAGE
123	71052501	TEST1482	1482	1489	ı	149	210	ì	PASTURE	FORAGE	FORAGE
124	71052501	TEST1131	1131	1142	1	47	58	1	HAY	FORAGE	FORAGE
125	71052501	TEST1403	1403	1416	1	130	150	1	HAY	FORAGE	FORAGE
126	71052501	TEST1499	1499	1517	ì	161	174	1	HAY	FORAGE	FORAGE
127	71052501	TEST1510	1510	1516	l	133	148	i -	HAY	FORAGE	FORAGE
128	71052501	TEST1496	1496	1501	1	107	126	ì	HAY	FORAGE	FORAGE
129	71052501	TEST1474	1474	1483	1	1	10	1	HAY	FORAGE	FORAGE
130	71052501	TEST94	94	99	ı	185	192	1	STUBBLE	FORAGE	FORAGE
131	71052501	TEST164	164	173	1	170	176	1	STUBBLE	FORAGE	FORAGE
132	71052501	TEST293	293	302	1	213	215	1	STUBBLE	FORAGE	FORAGE
133	71052501	TEST440	440	451	1	122	131	1	STUBBLE	FORAGE	FORAGE
134	71052501	TEST447	447	462	ì	467	172	1	STUBBLE	FORAGE	FORAGE
135	71052501	TEST529	529	532	1	108	120	L	STUBBLE	FORAGE	FORAGE
136	71052501	TEST689	689	704	1	110	113	1	STUBBLE	FORAGE	FORAGE
137	71052501	TEST696	696	703	1	88	93	ı	STUBBLE	FORAGE	FORAGE
138	71052501	TEST725	725	733	1	27	32	i	STUBBLE	FORAGE	FORAGE
139	71052501	TEST1016	1016	1021	ı	60	79	1	STUBBLE	FORAGE	FORAGE
140	71052501	TEST1221	1221	1252	1	61	69	1	STUBBLE	FORAGE	FURAGÉ
141	71052501	TEST1402	1402	1415	1	176	189	ì	STUBBLE	FORAGE	FORAGE
142	71052501	TEST1455	1455	1464	1	118	131	1	STUBBLE	FORAGE	FORAGE
143	71052501	TEST1062	1062	1068	1	156	172	1	STUBBLE	FORAGE	FORAGE
144	71052501	TEST1252	1252	1274	1	109	125	ì	STUBBLE	FORAGE	FORAGE
145	71052501	TEST1199	1199	1209	ì	173	183	1	STUBBLE	FORAGE	FORAGE
146	71052501	TEST650	650	660	1	174	181	ì	CORN	ROW	CORN
147	71052501	TEST698	698	700	1	154	169	1	CORN	ROW	CORN
148	71052501	TEST707	707	714	l	134	146	1	CORN	b (JM	CORN
149	71052501	TEST924	924	934	ı	159	169	1	CORN	ROW	CORN
150	71052501	TEST1212	1212	1248	1	172	193	1	CORN	RO₩	CURN
151	71052501	TEST1417	1417	1438	ı	157	167	1	CORN	ROW	CORN
152	71052501	TEST1482	1482	1512	1	52	82	1	CORN	MGa	CORN
153	71052501	TEST1482	1482	1492	1	85	103	1	CORN	ROM	CORN
154	71052501	TEST1503	1503	1512	1	152	157	1	CORN	ROW	CORN
155	71052501	TEST1510	1510	1513	ı	196	203	1	CORN	8 OM	CORN
156	71052501	TEST294	294	318	Ł	218	222	1	SDY	B OM	SOY
157	71052501	TEST706	706	711	1	190	194	1	SOY	ROW	SCY
158	71052501	TEST921	921	926	1	109	124	1	SOY	RUW	SOY
159	71052501	TEST1057	1057	1059	1	139	157	1	SOY	ROW	SOY
160	71052501	TESTIL01	1101	1112	-1	158	171	1	SOY	ROW	SGY
iól	71052501	TEST1144	1144	1161	ì	1	3	7	SOY	ROW	SOY
162	71052501	TEST1175	1175	1179	1	30	33	ì	SDY .	ROW	SOY
163	71052501	TEST1186	1186	1189	1	39	42	1	SOY	POW	YOZ
164	71052501	TEST1220	1220	1222	ı	11	30	1	SOY	#OM	SCY
165	71052501	TEST1215	1215	1218	1	46	51	1	\$8Y	RUW	\$0Y
166	71052501	TEST1192	1192	1196	1	13	26	1	SOY	RÓW	SOY
167	71052501	TEST125B	1258	1264	1	17	29	1	SDY	POW	SOY
168	71052501	TEST1420	1420	1442	l	129	140	1	SOY	ROW	YO2
169	71052501	TEST1420	1420	1429	1	143	152	1	SUY	ROW	YOZ
170	71052501	TEST1431	1431	1443	ì	143	150	1	SOY	ROW	\$0¥
171	71052501	TEST1466	1466	1478	1	33	45	1	SOY	ROW	SGY
172	71052501	TEST1477	1477	1479	1	49	76	1	SOY	ROW	\$0Y
173	71052501	TEST1508	1508	1514	1	107	122	1	SOY	POW	\$0¥
174	71052501	TEST1537	1537	1544	1	162	180	1	SOY	POW	SCY

Table 1A, cont.

				1156	1	1.7	42	1	SOY	ROW	SUY
		TEST1137				•			SOY	ROW	YOZ
176	71052501	TEST1131	1131	1136	1	32	43	r	301		cnv
1.0	11032301	TEST1156	1156	1165	1	L7	23	ı	SOY	₽ O W	SOY
177	71052501	16211130	1130			1.0	12	1	SBY	ROW	YOZ
178	71052501	TEST1140	1140	1165	L	10	1.4	•		B D I I	SOY
					1	15	28	1	SOY	ROW	50,

Table 2A

Training and test fields used for analysis of digitized color infrared photography: Run 71056903.

Table 2A

SAVED TRAINING FIELDS

						2AVE	TRAINE.	10 11000			
	RUN NJMBER	FIELD DESIG.	FIRST	LAST I	INE	FIRST	LAST	COLUMN	FIELD TYPE	OTHER INFORMATION	CLASSIFY CLASS
			1712	1744	Ĺ	337	344	ı	DECID	FOREST	DECID
1	71056903	TRN 1712 TRN 2506	2506	2520	1	91	105	ι	0EC19	FOREST	DECID
2	71056903	TRN 1428	1428	1434	1	135	141	ı	CONIFER	FUREST	CONTFER
3	71056903	TRN 1430	1430	1430	ì	153	151	ı	CONIFER	FOREST	CON1 FER
4	71056903	TRN 1442	1442	1446	1	135	137	1	CUNIFER	FOREST	CONTER
۶.	71056903 71056903	TRN 1450	1450	1450	1	147	157	ı	CONTER	FOREST	CONTFER
7	71056903	TRN 1480	1480	1490	ı	119	121	L	CONTEER	FJREST	CONTER
8	71056903	TRN 2076	2076	2086	1	183	197	ι	CONTFER	TRARCA	CONTREA
9	71056903	TRN 2208	2208	2212	1	229	251	1	CONTFER	FOREST	CONTER
10	71056903	TRN 1676	1676	1578	ı	6.3	69	1	POND	HATER	WATER
11	71056903	TRN 1660	1660	1664	t	205	217	ì	PONO	WATER	WATER
1.2	71056903	TRN 1666	1666	1674	1	211	221	ì	POND	WATER	WATER
13	71056903	TRN 1674	1674	1684	ı	223	237	1	DAD	WATER	WATER
14	71056903	C805 NAT	2080	2082	ì	225	231	1	POND	WATER	WATER
15	71056903	C481 PRT	1840	1842	i	121	123	1	POND	WATER WATER	WATER
16	71056903	TRN 3172	3172	3178	ì	69	77	1	POND	WATER	WATER
17	71056903	TRN 3196	3176	3202	1	51	59	1	90V9 90V9	WATER	WATER
18	71056903	TRN 3206	3,206	3214	ī	45	51	ì	PONO POND	WATER	WATER
L9	71056903	TRN 3276	3276	3276	ì		135	1	RIVER	WATER	WATER
20	71056903	TRN 3942	3942	3942	i	77	89		RIVER	WATER	WATER
21	71056903	TRN 3964	3964	3968	. 1		123	1		WATER	WATER
22	71056903	TRN 4028	4028	4030	i.		183 209			WATER	WATER
23	71056903	TRN 4035	4036	4038	1		203	1		WATER	WATER
24	71056903	TRN 4074		4092	1		197	1		WATER	WATER
25	71056903	TRN 4163		4178	ì				RIVER	WATER	WATER
26	71056903^	TRN 4202		4208	i,				RIVER	WATER	WATER
27	71056903	TRN 4194		4200	1				RIVER	WATER	WATER
28	71056903	TRN 3940		3940	1				L PASTURE	FURAGE	FORAGE
29	71056903	TRN 1404		1410 1478	,				1 PASTURE	FORAGE	FURAGE
30	71056903	TRN 1462		1782	,				1 PASTURE	FURAGE	FURAGE
31	71056903	TRN 1765		1810		l 1			PASTURE	FIIRAGE	FOR AGE
3.2	71056903	TRN 1792		2076		37			L PASTURE	FOR AGE	FORAGE
33	71056903	TRN 2064		2258		1 41		,	i PASTURE	FURAGE	FURAGE
34	71056903	TRN 2571		2604		1 41	3 443	3	L PASTURE	FORAGE	FURAGE
35		TRN 277		2788		1 14	7 161	i	1 PASTURE	FJRAGE	FORAGE
36		TRN 246		2468		1 18	7 204	9	1 PASTURE	FORAGE	FORAGE
37 36		TRN 315		3164		1 22	3 25	•	1 HAY	FURAGE	FORAGE
39		TRN 322		3234		1 29	7 34	3	1 HAY	FORAGE	FORAGE
40		TRN 388		3906		1 11	5 13	7	L HAY	FURAGE	FOR AGE FOR AGE
41		TRN 156		1578		1 33	3 34	7	1 STUBBLE	FORAGE	FORAGE
4		TRN 158	4 1584	1604		1 32	9 34	5	1 STUBBLE	FORAGE	FORAGE
4		TRN 284	0 2840	2846		1 34			1 STUBBLE		FURAGE
4		TRN 396	6 3966	3974		1 38			1 STUBBLE		FORAGE
4	5 71056903	TRN 400	2 4002	4014		1 36			1 STUBBLE		FURAGE
4	6 71056903	TRN 416	2 4162	4180	•	1 55			1 STUBBLE	PJW	CURN
4	7 71056903	TRN 280	2800	2822	<u> </u>	1 34			1 CORN 1 CORN	ROW	CORN
4	8 71056903	TRN 284	4 2844			1 . 28			1 CORN 1 CORN	RUW	CORN
4	9 71056903	TRN 285	2852			1 31			1 CORN	ROW	CORN
5	0 71056903					1 25			L CORN	RUW	CORN
5	1 7105690						19 23 21 23		1 CORN	ROW	CORN
5	2 7105690								1 CURN	ROW	CORN
5	3 7105690						01 44 25 25		1 SOY	ROW	Y02
5	4 7105690	_						77	1 SUY	ROW	YOZ
5	5 7105690							85	1 SQY	RÚW	¥89.
5	6 7105690							49	1 50Y	80%	SDY
	7105690							93	1 SOY	RUW	SUY
	8 7105690	3 TRN 41	06 410	6 416	4						

Table 2A, cont.

SAVED TEST FIELDS

	ji.										
	UN NUMBER	FIELD DESIG.	FIRST	LAST	LINE INT.	FIRST COLUMN	LAST COLUMN	EDEUMN INT.	FIELD	OTHER INFORMATION	DISPLAY CLASS
1	71056903	TEST1334	1334	1386	i	125	273	1	DECID	FUREST	DECID
2	71056903	TEST1422	1422	1440	1	213	269	ı	DECID	POREST	DECID
3	71056903	TEST1434	1434	1528	1	277	307	1	DECID	.FUREST	DECID
4	71056903	TEST1502	1502	1570	1	1	57	1	DECID	FOREST	DECID
5	71056903	TEST 1586	1586	1690	1	17	51	1	DECID	FOREST	DECID
6	71056903	TEST1484	1484	1526	1	199	245	1	DECID	FOREST	DECID
7	71056903	TEST1542	1542	1620	1	145	179	1	DECTO	FUREST	DECID
8	71056903	TEST1532	1532	1576	1	197	249	i	DECID	FOREST	DECID
9	71056903	TEST1532	1532	1590	1	281	309	1	DECID	FOREST	DECID
10	71056903	TEST1594	1594	1646	ì	221	241	ì	DECID	FOREST	06010
li	71056903	TESTloce	1668	1688	1	115	197	1	DECTO	FOREST	DECID
15	71056903	TEST1658	1658	1754	1	385	425	l.	DECID	FOREST	DECID
13	71056903	TEST1750	1750	1796	ì	215	297	1	DECID		01030
14	71056903	TEST1886	9881	1986	ı	95	123	1	01030	FOREST	DECID
15	71056903	16511988	1988	2036	ì	81	157	1	DEC 10	FOREST	DEC 10
16	71056903	TEST2038	2038	2134	l	71	119	l.	01030	FOREST	DECID
17	71056903	TEST1872	1872	1958	1	269	291	i	DECID DECID	FOREST	01030
18	71056903	TEST1862	1862	1902	1	325	379	1	DECID	FUREST	DECID
19	71056903	TEST 1876	1876	1902	1	361	419	1	DECID	FOREST	DECID
20	71056903	TEST2016	2016	2050	1	241	345	ı	DECID	FOREST	DECID
21	71056903	TEST2090	2090	2144	1	201	257	1	DECID	FOREST	DECID
22	71056903	TEST2076	2076	2108	l	313	353	1	DECIO	FUREST	DEC 10
23	71056903	TEST2148	2148	2192	1	235	361 169	1	DECID	FOREST	DECID
24	71056903	TEST2178	2178	2220	!	111	327	1	01030	FOREST	DECID
25	71056903	TEST2194	2194	2214	1	275 321	361	1	DECID	FUREST	01030
26	71056903	TEST2222	2222	2276	1	283	303	·	05010	FUREST	DECID
27	71056903	TEST2274	2274	2334	l l		307	1	DECID	FOREST	DECID
28	71056903	TEST2290	2290	2312 2394	1		95	1		FOREST	DECID
29	71056903	TEST2372	2372 2348	2418	1		419	1		FUREST	DECID
30	71056903	TEST2348	2464	2500	ì	_	271	1		FUREST	DECID
31	71056903	TEST2464	2506	2560	1	_	123			FOREST	DECID
32	71056903	TEST2506 TEST2604	2604	2686	ì		365		DECID	FOREST	DECID
33	71056903 71056903	TEST2732	2732	2772	ı		193		DEC10	FOREST	DECTO
34	71056903	TEST2730	2730	2770	1		443		DECID	FUREST	DECID
35	71056903	TEST2790	2790	2836	1		271	1	DECID	FUREST	DECID
36 37	71056903	TEST3086	3086	3168	i		405	1	DECID	FOREST	DECID
38	71056903	TEST3128	3128	3230	1	107	147	1	DECID	FUREST	DECID
39	71056903	TEST3228	3228	3262	1	361	443	. 1	DECID	FOREST	DECLD
40	71056903	TEST3408	3408	3502	1	139	249		L DECID	FUREST	DECID ~
41	71056903	TEST3578	3578	3708	- 1	369	425	. 1	DECID	FUREST	DEC 10
42	71056903	TEST3734	3734	3774	1	. 233	287	. 1	DECID	FOREST	DEC1D
43	71056903	TES13988	3988	4034	i	219	267	'	DECID	FOREST	DECID
44	71056903	TES#4344	4344	4378	1	387	443	: :	L DECID	FOREST	DECID
45	71056903	TEST2604	2604	2616	. 1	. 367	377		DECID	FOREST	DECID
46	71056903	TEST2096	2096	0015	. 1	173	181		CONIFER	FUREST	CONIFER
47	71056903	TEST2232	2232	2236	. 1	291	301		1 CONIFER	FOREST	CONTFER
48	71056903	TEST2238	2238	2258	. 1	277	285		CONTER	FOREST	CONTFER
49	71-056903	TEST2468	2468	2472	. 1	297			1 CONTER	FOREST	CONIFER HATER
50	71056903	TEST1978	1978	1980	:	291			1 PDND	WATER	WATER
51	71056903	TEST3180	3180	3190		1 59			POND	WATER	WATER
52	71056903	TEST4026	4026	4065	. :	1 59			RIVER	WATER	WATER
5.3	71056903	TEST4020	4020	4022		1 154			I RIVER	WATER	WATER
54	71056903	TEST4038	4038	4056		1 204			1 RIVER	WATER	WATER
55		TEST4104		4122		20			1 RIVER	WATER WATER	WATER
56		TEST4216		4222		1 26:			1 RIVER	WATER	WATER
57		TEST4170		41.76		1 319			I RIVER	WATER	WATER
58				4160		1 329				WATER	WATER
59				4144		1 32			1 RIVER 1 RIVER	WATER	WATER
60						1 33			I RIVER	WATER	WATER
51						1 33			1 RIVER	WATER	HATER
62						1 33			i RIVER	WATER	WATER
6.3						1 33 1 34			i RIVER	WATER	WATER
6.4	71056903	TEST3976	5 3976	275.	c	, 24	. ,,,				

Table 2A, cont.

55	71056903	TEST1348	1348	1362	ı	59	15	1.	PASTURE	FORAGE	FURAGE
	71056903	TEST1584	1584	1636	1	391	405	ŀ	PASTURE	FURAGE	FORAGE
	71056903	TEST1626	1626	1638	ı	271	335	1	PASTURE	FORAGE	FORAGE
	71056903	TEST1642	1642	1650	ı	279	∠97	ı	PASTURE	FARAGE	FURAGE
69	71056903	TEST1736	1736	1744	i	209	251	. k	PASTURE	FIRAGE	FORAGE
70	71056903	TESTIBLO	1810	1816	ì	235	249	t	PASTURE	FURAGE	FORAGE
71	71056903	TEST1842	1842	1858	1	231	253	i .	PASTURE	FURAGE	FORAGE
72	71056903	16511850	1850	1864	t	283	303	i.	PASTURE	FORAGE	. FORAGE FORAGE
13	71056903	TEST1922 -	1922	1940	l	395	429	ì	PASTURE	FURAGE	FURALE
74	71056903	16571960	1960	1986	1	241	253	i .	PASTURE	FJRAGE FURAGE	FORAGE
75	71056903	TEST1 972	1972	1982	ı.	267	283	i I	PASTURE PASTURE	FURAGE	FORAGE
16	71056903	TEST1 +92	1992	200a	į.	287	275 137	i	PASTURE	FORAGE	FORAGE
77	71056933	TEST2064	2064	2082	i .	125 279:	109	1	PASTURE	FIRAGE	FURAILE
76	71056903	18512106	2106	2118	1	137	151	1	PASTURE	FORAGE	FORAGE
79	71056903	TEST7238	2238	2250 2216	i	375	413	1	PASTURE	FURAGE	FORAGE
80	71056903	TEST2172	2172 2262	2290	1	405	419	ı	PASTURE	FURAGE	FORAGE
91	71056903	TEST2262	2280	2288	ا د	н9	103	1	PASTURE	FIRAGE	FORAGE
8.2	71056903	TEST2280 TEST2344	2344	2364	1	241	255	i	PASTURE	FURAGE	FURAGE
63	71056903 71056903	TEST2346	2346	2364	ì	343	363	I.	PASTURE	FURAGE	FURAGE
£1.4 ₩5	71056903	TEST2368	2368	Z404	1	335	359	i.	PASTJRE	FBRAGE	FORAGE
86	71056903	TEST2385	2386	2432	i	157	175	ı	PASTURE	CHRAGE	FURAGE
87	71056933	TEST2444	2444	2466	ı	95	113	£	PASTURE	FIRAGE	FURAGE
нв	71056903	T:572444	2444	2466	i	137	153	l.	PASTURE	FJRAGE	FURALE
H.9	71056903	TEST2422	2422	2449	1	181	217	1	PASTURE	FJRAGE	FORAGE
3 0	71056903	TES12405	2406	2430	1	305	323	1	PASTURE	FUKALE	FURAGE
91	71056903	TEST2506	2506	2554	1	223	239	ı	PASTURE	FURAGE	FURAGE
92	71056903	TEST2538	2538	2554	1	273	293	1	PASTURE	FARAGE	FORAGE
73	71056903	TEST2575	2576	2590	ì	103	129	1	PASTURE	FURAGE	FURAGE
74	71056903	TEST2602	2602	2620	t	147	161	I.	PASTURE	FURAGE	FURAGE
95	71056903	TES 2584	2584	2596	l.	215	341	į.	PASTURE	FORAGE	FOR AGE FOR AGE
96	71056903	TEST2626	2626	2642	. 1	409	443	i .	PASTURE	FJRAGE FURAĢ€	FÜRAGE
97	71056903	TEST2706	2706	2/30	i	207	231	1	PASTURE	FIRAGE	FURAGE
98	71056903	TEST2740	7740	2768	1	283	305	1	PASTURE PASTURE	FORAGE	FORAGE
99	11056903	16512770	2710	2806	i .	279	341	1	PASTURE	F:)RAGE	FORAGE
100	71056903	TESF2772	2772	2780	1	385	425 269	i	PASTURE	FURAGE	FURAGE
101	71056903	TEST2874	2874	2904	1	253	409	1	PASTURE	FURAGE	FORAGE
102	71056903	TE512893	2890	2900	1	155 237	2R1	1	PASTURE	FJRAGE	FORAGE
103	71056903	TEST3290	3290	3304	ì	109	133	1	PASTURE	FURAGE	FÜRALE
104	71056903	TEST3350	3350	3360	i L	339	367	1	PASTURE	f.JRAGE	FURAGE
135	71056903	TEST3448	3448 3486	3484 3498	1	315	353	ı	PASTURE	FURAGE	FURAGE .
106	71056903	TEST 3486	35 30	3544	Ĺ	233	275	L	PASTURE	FURAGE	FORAGE
107	71056903	TEST3530 TEST3608	3608	3648	1	119	135	1	PASTURE	FURAGE	FURALE
108	71056903 71056903	TEST 3728	3728	3748	ı	307	349	1.	PASTURE	FUKAGL	FORAGE
110	71056903	16ST3754	3754	3774	1	167	207	ì	PASTURE	FIRAGE	FURAGE
111	71056903	TEST3832	3832	1846	1	249	289	1	PASTURE	FORAGE	FURAGE
112	71056933	TE513848	3848	3868	1	251	109	i	PASTURE	FHRAGE	FORAGE
113	71056903	TEST 3950	3950	3966	t	265	241	1	PASTURE	FIRAGE	FURAGE
114	71056903	TE5T3414	3914	3942	1	351	373	ŧ	PASTURE	T JK 4GE	FURAGE
115	71056903	TEST3990	3990	4006	1	291	317	1	PASTURE	FURAGE	FURAGE
116	71056903	16514250	4250	4262	ŧ	341	373	ì		FURAGE	FORAGE
117	71056903	TEST4322	4322	4364	1	159	181	ı		FJRAGE	FORAGE
118	71056903	TEST4362	4362	4398	1	345	371	1		FORAGE	FORAGE
119		TEST4424	4424	4442	i	367	443	1		FURAGE	FURAGE
126	71056903	TES11692	1692	1702	1	321	, 3 3	1		FURAGE	FORAGE
121	71056903	TEST3854	3854	3886	k	113	143	1		FORAGE	FORAGE FORAGE
155		TEST4452	4452	4486	i	281	329	j.		FURAGE	FURAGE
123		TEST 1536	1536	1546	1	323	339			FURAGE	FORAGE
124		16511690	1640	1714	1	365	317	1		FURAGE	FURAGE
125	71056903	TEST1970	1970	1990	l.	344	407		L STUBALE	FJRAGE FURAGE	FORAGE
126		TEST2302	2302	2328	1	253	263		L STUBBLE	FURAGE	FURAGE
127		TEST2314	2314	2350	Ţ	323	333		STUBBLE STUBBLE	FURAGE	FORAGE
128		TEST2506	2506	2514	1	245	251			FURAGE	₩ FURAGE
129	71056903	TEST2880	2880	5900	- 1	211	,271		1 ZINBRFE	TORNOC	COUNCE

Table 2A, cont.

			200	2968	1	99	121	ı	STUBBLE	FORAGE	FORAGE
131	71056903	TEST2950	2950		l	167	207	Ł	STUBBLE	FORAGE	FORAGE
132	71056903	TEST3596	3596	3606		313	351	ı	STUBBLE	FURAGE	FORAGE
133	71056903	TEST3698	3698	3708	ì	355	383	ı	STUBBLE	FURAGE	FORAGE
134	71056903	TEST3990	3940	4016	l.	171	185	ì	STUBBLE	FORAGE	FORAGE
135	71056903	TEST4040	4040	4104	1		275	1	STUBBLE	FORAGE	FURAGE
136	71056903	TEST4104	4104	4160	1	251	393	ı	STUBBLE	FORAGE	FORAGE
137	71056903	TEST4448	4448	4474	1	371	361	1	CORN	ម DM	CORN
138	71056903	TEST2772	2772	2798	1	349	339	1	CORN	RÜW	CORN
139	71056903	TEST2886	2886	2890	ì	313		1	CORN	ROW	CORN
140	71056903	TEST2905	2906	2928	1	283	305		CORN	RUW	CORN
141	71056903	TEST3386	3386	3414	. 1	319	341	1	CORN	ROW .	CORN
142	71056903	TEST4022	4022	4104	1	355	427	i		ROW	SOY
143	71056903	TEST1970	1970	2022	1	413	423	1	SDY	ROW	SOY
144	71056903	TEST2904	2904	2920	1	375	389	1	SOY	R J w	SOY
145	71056903	TEST 3380	3380	3396	l	233	261	1	YOS	ROW ROW	SOY
146	71056903	TEST3690	3690	3694	ì	283	329	1	SOY		SOY
147	71056903	TEST3784	3784	3808	1	327	349	. 1	50Y	RON	SüY
148	71056903	TEST3880	3880	3912	1	45	55	ì	SUY	e GM	SOY
149	71056903	TEST3874	3874	3912	ı	67	73	ı	SOY	RUW	, SOY
150	71056903	TEST3868	3868	3916	1	83	111	L	SUY	ROW	, 301 YO2
151	71056903	TEST3918	3918	3926	1	85	101	7	SUA	R ()₩	201 201
152	· ·	TEST 3940	3940	3952	1	113	123	ì	SOY	P OW	
153		TEST3970	3970	3976	1	137	143	. 1	SOY	R.3W	\$0 Y
154		TEST3978	3978	3988	1	75	113	1	SOY	RUW	SOY
155		TEST3992	3992	4006	1	75	121	1	SOY	ROW	50Y
156		TEST4038	4038	4042	1	71	111	· l	SOY	ROM	SOY
_	71056903	TEST4024	4024	4034	1	143	155	1	\$0Y	ROW	SOY
157			4124	4134	1	87	113	1	SOY	RUW	Y D 2

APPENDIX B

Table 1B. Test class performance using best one channel.

CHANNELS	SUSED

				9	
CHANNEL 10	SPECTRAL BAND	1.50 TO	1.80 MICROMETERS	CALIBRATION CODE = 1	CO * 0.0

CLASSES

	CLASS	•	CLASS
1	DECID	4	FORAGE
2	CONTEER	5	CORN
3	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER OF SAMPLES CLASSIFIED INTO				
	GROUP	NO OF SAMPS	CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
1	DECID	32252	43.1	13890	5842	45	1	11777	697
2	CONIFER	88	84.1	12	74	1	0	1	0
3	WATER	339	95.9	8	6	325	0	0	0
4	FORAGE	11760	27.6	32	17	0	3241	1629	6841
5	CCRN	2679	80.1	215	0	0	0	2147	317
6	SOY	2676	84.2	4	0	0	13	405	2254
-	TOTAL	49794		14161	5939	371	3255	15959	10109

OVERALL PERFORMANCE(21931/ 49794) = 44.0 AVERAGE PERFORMANCE BY CLASS(415.0/ 6) = 69.2

Table 2B. Test class performance using best combination of two channels.

СН	ANN	EL	S	US	ΕD	

CHANNEL 6	SPECTRAL BAND	0.58 TO	0.65 MICROMETERS	CALIBRATION CODE = 1	C0 = 0.0
CHANNEL 10	SPECTRAL BAND	1.50 TO	1.80 MICROMETERS	CALIBRATION CODE = 1	C0 = 0.0

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLES	CLASSIF	IED INTO	
	GROUP	NO OF SAMPS	CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
1	DECID	32252	87.1	28094	2005	10	271	386	1486
2	CONTER	88	87.5	8	77	2	0	1	0
3	WATER	339	97.9	4	2	332	0	1	0
4	FORAGE	11760	55.9	16	9	9	6574	2402	2750
5	CORN	2679	88.1	2	2	0	0	2361	314
6	YOZ	2676	98.2	8	0	0	13	27	2628
	TOTAL	49794		28132	2095	353	6858	5178	7178

OVERALL PERFORMANCE(40066/ 49794) = 80.5

AVERAGE PERFORMANCE BY CLASS(514.8/ 6) = 85.8

Table 3B. Test class performance using best combination of three channels.

CHANNEL 6	SPECTRAL BAND	0.58 TO 0.65 MICROMETERS	CALIBRATION CODE = 1	C0 = 0.0
CHANNEL 10	SPECTRAL BAND	1.50 TO - 1.80 MICROMETERS	CALIBRATION CODE = 1	CO = 0.0
CHANNEL 12	SPECTRAL BAND	9.30 TO 11.70 MICROMETERS	CALIBRATION CODE = 1	CO = 32.70

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	WATED	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLES	CLASSIFIED INTO		
	GROUP	NO OF Samps	PCT. CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
ì	DECID	32252	88.8	28640	1700	0	573	292	1047
2	CONIFER	88	95.5	3	84	0	1	0	0
3	WATER	339	98.2	0	2	333	2	· 2	0
4	FORAGE	11760	80.6	17	6	5	9483	750	1499
5	CORN	2679	84.8	2	1	C	7	2272	397
6	SOY	2676	95.2	4	0	0	105	20	2547
	TOT AL	49794		28666	1793	338	10171	3336	5490

OVERALL PERFORMANCE(43359/ 49794) = 87.1

AVERAGE PERFORMANCE BY CLASS(543.1/ 6) = 90.5

Table 4B. Test class performance using best combination of four channels.

CHANNEL 4	SPECTRAL BAND	0.52 10 0.57	MICROMETERS	CALIBRATION	CODE = 1	C0 = 0.0
CHANNEL 6	SPECTRAL BAND	0.58 TO 0.65	MICROMETERS	CALIBRATION	CODE = 1	£0 = 0.0
CHANNEL 10	SPECTRAL BAND	1.50 TO 1.80	MICROMETERS	CALIBRATION	CODE = 1	CO = 0.0
CHANNEL 12	SPECTRAL BAND	9.30 TO 11.70	MICROMETERS	CALIBRATION	CODE = 1	00 = 32.70

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
. 2	CONTEER	5	CORN
3	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLES	CLASSIF	IED INTO	
	GROUP	NO DE SAMPS	CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
1	DECID	32252	89.9	28987	1615	0	405	288	957
2	CONIFER	88	96.6	3	85	0	0	0	. 0
3	WATER	339	97.6	1	2	331	4	ì	0
4	FORAGE	11760	84.8	20	3	2	9977	480	1278
5	CORN	2679	94.2	1	2	0	104	2524	48
6	SOY	2676	96.2	6	0	0	70	25	2575
	TOTAL	49794		29018	1707	333	10560	3318	4858

OVERALL PERFORMANCE(44479/ 49794) = 89.3 AVERAGE PERFORMANCE BY CLASS(559.4/ 6) = 93.2



Table 7B. Test class performance using best combination of eight channels.

CHANNEL	4	SPECTRAL	BAND	0.52	TO	0.57	MICROMETERS	CALIBRATION	CODE	= 1	CO =	0.0
CHANNEL	6	SPECTRAL	BAND	0.58	TO	0.65	MICROMETERS	CALIBRATION	CODE	= 1	€0 =	0.0
CHANNEL	7	SPECTRAL	BAND	0.61	TO	0.70	MICROMETERS	CALIBRATION	CODE	= 1	CO =	0.0
CHANNEL	8	SPECTRAL	BAND	0.72	TO	0.92	MICROMETERS	CALIBRATION	CODE	= 1	CO =	0.0
CHANNEL	9	SPECTRAL	BAND	1.00	TO	1.40	MICROMETERS	CALIBRATION	CODE	= 1	CO =	0.0
CHANNEL	10	SPECTRAL	BAND	1.50	TO	1.80	MICROMETERS	CALIBRATION	CODE	= 1	C0 =	0.0
CHANNEL	11	SPECTRAL	BAND	2.00	TO	2.60	MICROMETERS	CALIBRATION	CODE	= 1	CO =	0.0
CHANNEL	12	SPECTRAL	BAND	9.30	TO	11.70	MICROMETERS	CALIBRATION	CODE	= 1	€0 =	32.70

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLE	S CLASSIF	IED INTO	
	GROUP	NO OF Samps	CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
1	DECIB	32252	96.2	31036	402	C	290	169	355
2	CONTFER	88	96.6	3	85	0	0	. 0	0
3	WATER	339	98.5	1	1	334	. 3	0	0
4	FORAGE	11760	85.8	53	6	2	10090	342	1267
5	CORN	2679	93.8	0	1	0	152	2512	14
6	SOY	2676	96.3	5	1	0	75	17	2578
	TOTAL	49794		31098	496	336	10610	3040	4214

OVERALL PERFORMANCE(46635/ 49794) = 93.7 AVERAGE PERFORMANCE BY CLASS(567.2/ 6) = 94.5

Table 8B. Test class performance using best combination of ten channels.

						CH	ANNELS USED	4						
CHANNEL	2	SPECTRAL	BAND	0.48	то	0.51	MICROMETERS	CALIBRATION	CODE	=	1	co	=	0.0
CHANNEL	3	SPECTRAL	BAND	0.50	TO	0.54	MICROMETERS	CALIBRATION	CODE	=	1	CO	×	0.0
CHANNEL	4	SPECTRAL	BAND	0.52	10	0.57	MICROMETERS	CALIBRATION	CODE	=	1	CO	≖.	0.0
CHANNEL	6	SPECTRAL	BAND	0.58	TO	0.65	MICROMETERS	CALIBRATION	CODE	=	1	CO	=	0.0
CHANNEL	7	SPECTRAL	BAND	0.61	ro	0.70	MICROMETERS	CALIBRATION	CODE	=	ì	CO	×	0.0
CHANNEL	8	SPECTRAL	BAND	0.72	TO	0.92	MICROMETERS	CALIBRATION	CODE	=	1	CO	=	0.0
CHANNEL	9	SPECTRAL	BAND	1.00	ro	1.40	MICROMETERS	CALIBRATION	CODE	=	1	03	*	0.0
CHANNEL		SPECTRAL	BAND	1.50	TO	1.80	MICROMETERS	CALIBRATION	CODE	=	1	CO	± ,	0.0
CHANNEL		SPECTRAL		2.00	TO	2.60	MICROMETERS	CALIBRATION	CODE	=	1	CO	*	0.0
CHANNEL		SPECTRAL		9.30	TO	11.70	MICROMETERS	CALIBRATION	CODE	=	1	CO	#	32.70

CLASSES

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3 0	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLES	CLASSIF	IED INTO	
	GROUP	NO DE Samps	PCT. CORCT	DECID	CONIFER	WATER	FURAGE	CORN	YCZ
1	DEC.10	32252	97.0	31271	376	0 "	258	97	240
Z	CONIFER	88	96.6	3	85	0	3	0	. 0
3	WATER	339	98.5	1	1	334	3	3	0
4	FORAGE	11760	87.8	45	6	2	10325	284	1098
5	CORN	2679	95.6	1	2	0	100	2561	15
6	SDY	2676	96.3	4	1	0	76	17	2578
	TOTAL	49794		31325	471	336	10772	2959	3931

OVERALL PERFORMANCE(47154/ 49794) = 94.7 AVERAGE PERFORMANCE BY CLASS(571.8/ 6) = 95.3

Table 9B. Test class performance using all twelve channels.

CHANNEL	1	SPECTRAL B	AND	0.46	10	0.49	MICROMETERS	CALIBRATION	CODE	= 1	CO :	-	0.0
CHANNEL	2	SPECTRAL B	SAND	0.48	то	0.51	MICROMETERS	CALIBRATION	CODE	= 1	CO.	=	0.0
CHANNEL	3	SPECTRAL B	BAND	0.50	10	0.54	MICROMETERS	CALIBRATION			CO		- •
CHANNEL	4	SPECTRAL 8	BAND	0.52	TO	0.57	MICROMETERS	CALIBRATION	-				0.0
CHANNEL	5	SPECTRAL E					MICROMETERS	CALIBRATION			0.0		
CHANNEL	6	SPECTRAL E					MICROMETERS	CALIBRATION			CO		
CHANNEL	7	SPECTRAL B					MICROMETERS	CALIBRATION			•-		0.0
CHANNEL	8	SPECTRAL E					MICROMETERS	CALIBRATION					0.0
CHANNEL	9	SPECTRAL E					MICROMETERS	CALIBRATION					0.0
CHANNEL	10	SPECTRAL &					MICROMETERS	CALIBRATION					0.0
CHANNEL	11	SPECTRAL E					MICROMETERS	CALIBRATION			-		32.70
CHANNEL	12	SPECTRAL E	BAND	9.30	TO	11.70	MICROMETERS	CALIBRATION	CODE	= T	CO	-	32410

CFWZZFZ

	CLASS		CLASS
1	DECID	4	FORAGE
2	CONIFER	5	CORN
3	WATER	6	SOY

TEST CLASS PERFORMANCE

					NUMBER O	F SAMPLE	S CLASSIF	TED INTO	
	GROUP	NO OF SAMPS	CORCT	DECID	CONIFER	WATER	FORAGE	CORN	SOY
1.	DECID	32252	97.2	31339	359	0	263	112	179
2	CONTEER	88	95.5	4	84	0	0	0	0
3	WATER	339	98.5	1	1	334	3	၁	0
4	FORAGE	11760	88.6	39	5	1	10420	245	1050
5	CORN	2679	96.9	i	2	0	61	2597	18
6	SOY	2676	96.3	5	1	0	74	18	2578
	TOTAL	49794		31389	452	335	10821	2972	3825

OVERALL PERFORMANCE(47352/ 49794) = 95.1 AVERAGE PERFORMANCE BY CLASS(573.0/ 6) = 95.5

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13. ABSTRACT

Remote sensing equipment and automatic data processing techniques offer much potential for the procurement of information necessary to meet the demand for more intensive management of our forest resources.

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On the basis of automatically calculated statistics derived from manually-selected training samples, the feature selection processor of LARSYS was directed to select, upon consideration of various groups of the four available spectral regions, a series of "best" channel combinations whose automatic classification performances (for six cover types, including both deciduous and coniferous forest) were tested, analyzed and further compared with automatic classification results obtained from digitized color infrared photography.

Results indicated: 1) that the use of five, of the available 12, channels offers an acceptable compromise between classification accuracy and computer time; 2) that five channels (one each from the visible green and red, and the near, middle and thermal infrared) can classify basic forest cover with accuracies well in excess of 90 percent; 3) that a combination of the visible region plus either the near or middle infrared will provide sufficient spectral information for accurate basic forest cover mapping; and 4) that the qualitative nature of photographic data does not lend itself to reliable quantitative analysis.

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