

LARS Information Note 111774

Computer Analysis of ERTS-1
Imagery and Mapping of
Surficial Deposits in a Test
Area Within the Monticello
North Quadrangle, Ind.

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COMPUTER ANALYSIS OF ERTS-1 IMAGERY AND MAPPING
OF SURFICIAL DEPOSITS IN A TEST AREA WITHIN THE
MONTICELLO NORTH QUADRANGLE, INDIANA, USA.

by

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Abstract

Surficial deposits with and without vegetative canopies have been mapped using automatic data processing techniques developed at LARS on ERTS-1 multispectral data. Due to the reflectance patterns in an area covered by vegetation the resulting map suggests details that cannot be obtained by conventional air photointerpretation of color IR (scale 1:120,000) photography. In addition different scales of reproduction of ERTS-1 data maps are also discussed.

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Fig. 1. Location map. The arrow shows the Monticello north quadrangle area in the state of Indiana.

Introduction

The pattern of the surficial deposits in a test area of the Monticello north quadrangle (Fig. 1) has been analyzed by the use of multispectral scanner data collected by ERTS-1 (LARS Run 73033710; June 9, 1973) for the purposes of:

1. Comparing the automatic data processing techniques of LARS with traditional air-photointerpretation methods used in mapping.
2. Evaluation of the resolution of ERTS-1 data for mapping at various scales.

Data Processing

The LARSYS software system is a package of computer programs which has been designed for the analysis of remotely sensed multispectral data (Landgrebe, 1974). The advantage of this system is that it enables an analyst to undertake problems involving quantities of data too large to be efficiently interpreted by regular photointerpretation techniques. As with the standard methods for photointerpretation, the automatic recognition of patterns requires development of training areas. These training areas can either be obtained through field studies, former mapping/field descriptions or through contemporary photointerpretation.

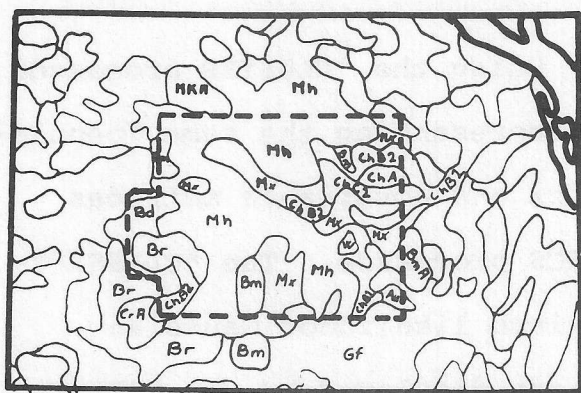
Otherwise, the function of the automatic classifying system of LARS is quite different from conventional photointerpretation (Cardillo and Landgrebe, 1966). The automatic recognition of patterns is based on a statistical evaluation of reflected energy in the electromagnetic field. In the LARS system, the analyst instructs the computer to analyze the magnitude and variance of the spectral responses of the material identified in the training areas and then to identify all areas in the rest of the scene with similar signatures.

Four channels of digital MSS data were analyzed [channel 4 (0.5 - 0.6 μm), channel 5 (0.6 - 0.7 μm), channel 6 (0.7 - 0.8 μm)

and channel 7 (0.8 - 1.1 μm)]. Using the *CLUSTER processor of LARSYS (Swain, 1972), units representing the same "populations" are grouped. Mean vectors and covariance matrices are calculated by the *STATISTICS processor. The *CLASSIFY-POINTS processor performs a maximum likelihood Gaussian classification and the results are displayed by the *PRINT-RESULTS processor.

Discussion of the Results

As shown in Fig. 2 the computer processed map and the map constructed by the use of the ordinary methods of photo-interpretation are similar. In both cases the same marked rectangular feature is seen in the central parts of the maps. This feature represents an area of deciduous trees. Neither the methods used in traditional air-photointerpretation nor the (first) automatic data processing could detect any reflectance patterns due to the underlying surficial deposits. However, different types of deciduous trees may reflect different characteristics in the various surficial deposits (Hoffer and Johannsen, 1969; Kristof, 1970). The surrounding areas of somewhat poorly and very poorly drained soils (Baumgardner, et al., 1970; Kristof and Zachary, 1971) indicate that these soils also appear inside this area. For the purpose of solving this problem, the rectangular area (line 917-926; column 1285-1298 and line 921-924; column 1284-1285 in Fig. 2) was repro-



II
0 1 km

Soil:

Drainage:

Soil	excess- sively somewhat excessi- well	moderate- ly well	somewhat poorly	very poor-
Au: Aubbeenaubee fsl				X
Bd: Brady fsl				X
Br: Brookston cl				X
Bm: Brems lfs				X
BmA: Brems lfs		X		
CrA: Crosier l				X
ChC2:Chelsea fs	X			
ChB2:Chelsea fs	X			
Gf: Gilford fsl				X
MkA: Metea lfs		X		
Mh: Maumee lfs				X
Mx: Morocco lfs				X
W: Water				

1111111111111111
2222222222222222
8888889999999999
567890123456789

917 FCCCCCCDCCCCRRDA
918 FCCCHBCCBCCDDDA
919 FDCCCCCCCCDFFDA
920 FDCCCCCCCCCCFDA
921 FDCCCCCCCCCCCCDD
922 FCBBBBCCCCBCCCCD
923 FCBBBBCCCCBFFCCA
924 NCBBBBDDDCBBBBD
925 FDBBDDDBBCCCCD
926 FABBBDDCCCCRDF

I
0 1km

Number of points per cluster:

Cluster	1	2	3	4	5
Symbol	A	B	C	D	F
Points	6	36	75	27	14

Cluster points means

		CH (1)	CH (2)	CH (3)	CH (4)
1	6	38.83	39.50	51.33	25.67
2	36	27.94	17.83	56.75	32.94
3	75	26.43	16.63	50.81	30.69
4	27	31.37	23.04	48.52	26.70
5	14	31.07	26.07	36.00	18.57

Separability information:

I	J	D(I,J)	D(I)	D(J)	D(J)+D(I)	QUOT
1	2	25.891	10.724	4.533	15.257	1.697
1	3	26.508	11.643	3.126	14.769	1.795
1	4	18.323	12.357	6.623	18.980	0.965
1	5	22.935	7.990	10.252	18.242	1.257
2	3	6.639	4.333	4.954	9.287	0.715
2	4	12.063	4.308	6.541	10.850	1.112
2	5	26.736	4.300	10.251	14.550	1.837
3	4	9.312	3.286	6.065	9.352	0.996
3	5	21.844	4.328	9.930	14.258	1.532
4	5	15.236	6.829	10.379	17.208	0.885

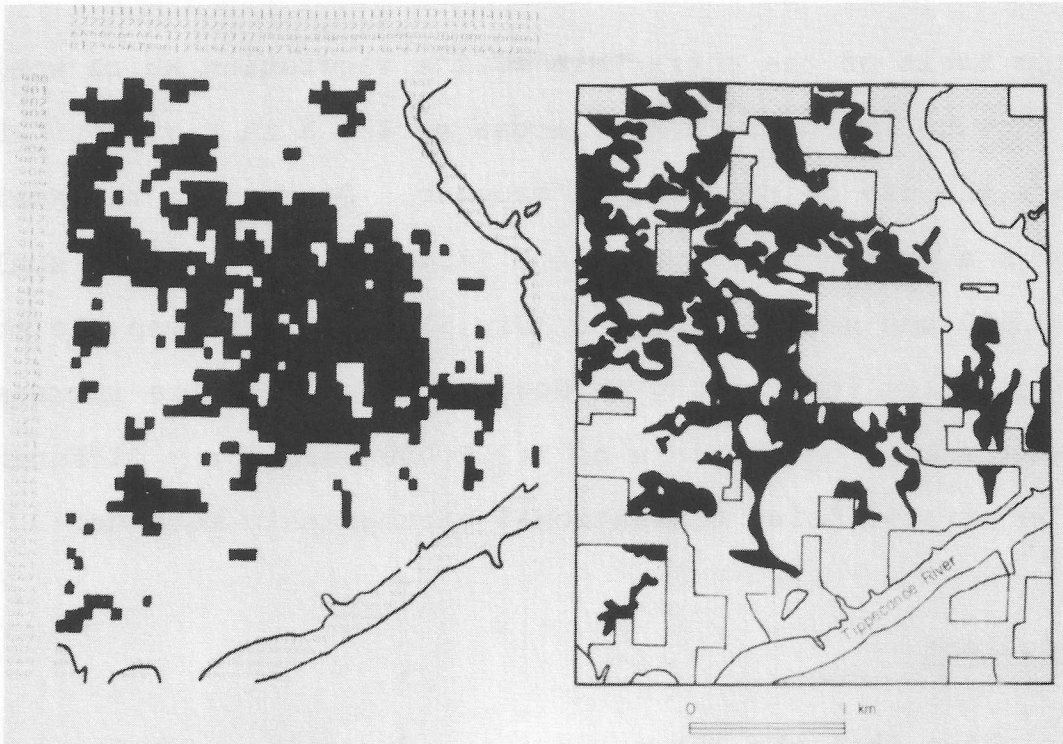
Cluster variances :

	CH (1)	CH (2)	CH (3)	CH (4)
1	11.77	37.50	7.47	6.27
2	2.63	3.86	3.22	2.68
3	1.33	1.70	5.24	3.49
4	4.47	8.35	10.26	4.91
5	7.61	23.46	23.69	11.19

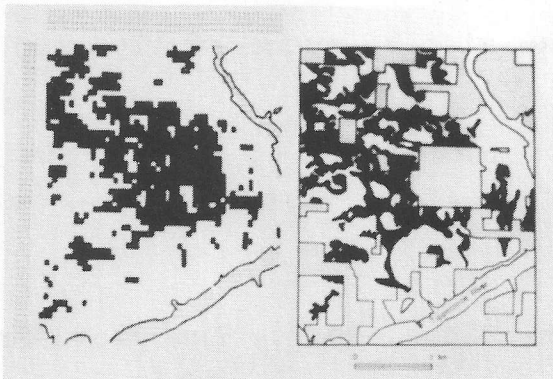
Fig. 3 - I. Reclustered area (line 917-926, column 1285-1298; line 912-924, column 1284).
II. Present soil map.

cessed using the *CLUSTER processor and the results are shown in Fig. 3I. A similarity measurement computed by the cluster processor indicated that classes 2 (B) and 3 (C) are spectrally similar. The symbols "B" and "C" match the surrounding areas of somewhat poorly and very poorly drained soils in Fig. 2. The same case prevails for the symbol "F", while the symbols "A" and "D" at the "edges of the feature" match the well- and moderately well-drained soils (cf. Fig. 2). This is also shown by comparison to the existing soil map in the area (Fig. 3II). On this basis it is suggested that the areas symbolized as either "B", "C" or "F" be matched to the somewhat poorly/very poorly drained soil even though the numbers of the points are too few for any statistics/classifypoints processing. The other parts of this area (symbolized as "A" and "D") are thought to consist of well/moderately well-drained soil.

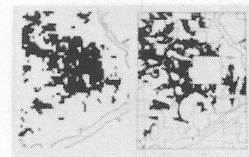
The areas (X) outlined in Fig. 2 are all reprocessed by the same methods, and the results are displayed in Figure 4. Due to the resolution of ERTS-1 the smallest area which can be "seen" is 59 m x 73 m (1.1 acre). In this case one symbol in Fig. 4 is equal to one resolution unit. Fig. 4 shows that some of the details that can be traced in a map based on color IR imagery are lost (due to the resolution areas of ERTS) in the printresults map. On the other hand it has been possible through a reprocessing of the MSS data to map soil differences



Scale 1 : 50 000



Scale 1 : 100 000



Scale 1 : 200 000

Fig. 5. The mapped area reprocessed photographically in different scales. For legend, see Fig. 2.

on the basis of the characters of the vegetation which would not show up in color IR (cf. areas marked A in Fig. 4). This favors the use of MSS data in mapping. Decreasing the scale through a photographic processor [i.e. scale 1:50,000, scale 1:100,000 and scale 1:200,000 (Fig.5) which has been the most common scales for mapping in Norway] these two maps increase in similarity. At a scale of 1:200,000 hardly any differences can be printed using conventional cartographic methods.

Conclusions

It is shown that the automated data processing techniques developed at LARS on ERTS-1 multispectral data are a useful supplement to conventional photo interpretation of the surficial deposits. In this case the data collected by ERTS-1 seem to favor small scaled maps, but can also be successfully used in large-scale mapping.

Acknowledgement

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